

Migrating to xWR68xx and xWR18xx Millimeter Wave Sensors



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ABSTRACT

This application report provides guidance for porting mm-wave hardware and application software to the xWR68xx ES2.0 and the xWR18xx devices.

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1 Introduction

The information presented here is applicable to any of the following scenarios:

- Have hardware/software currently deployed on xWR6843 ES1.0 and want to migrate it to xWR6843 ES2.0
- Have hardware/software currently deployed on xWR1642 and want to migrate it to xWR6843 ES2.0
- Have hardware/software currently deployed on xWR1642 and want to migrate it to xWR1843
- Have hardware/software currently deployed on xWR6843AOP ES1.0 and want to migrate to xWR6843AOP ES2.0

The information presented in this document covers:

- Comparison of the base and the new target device along-with a description of how those differences impact existing hardware and software.
- SDK version required for the new target device and updates needed in application build infrastructure (makefiles and/or CCS projects, linker command files, and so forth)
- Updates needed in application source code, for example, API updates, new structure parameters, and so forth.
- Example source code comparison snapshots are provided for easy reference.

For information specific to your current and target device, see the following sections.

Table 1-1. Migration Reference

Current Device	Target Device	Section
xWR6843 ES1.	xWR6843 ES 2.0	Migrating from xWR6843 ES1.0 to xWR6843 ES2.0 : Section 3.2
xWR1642	xWR6843 ES2.0	Migrating from xWR1642 to xWR6843 ES2.0 : Section 2.1
xWR1642	xWR1843	Migrating from xWR1642 to xWR1843 : Section 2
xWR6843AoP ES1.0	xWR6843AoP Es2.0	Migrating from xWR6843AoP ES1.0 to xWR6843AoP ES2.0 : Section 3

2 xWR1843 Hardware/Software Migration

This section provides migration guidance to port Hardware and software from the xWR1642 to the xWR1843 device. The information provided here is meant to cover the major changes for migrating to a particular MMWAVE-SDK release at the time of writing. For more information, see the *Migration* section in the [MMWAVE-SDK Release Notes](#).

2.1 Migrating From xWR1642 to xWR1843

2.1.1 Device Comparison

[Table 2-1](#) lists the key features of the xWR1642 and the xWR1843 devices that need to be considered from Hardware and software migration perspective. For more information, see the device-specific data sheets and the *Industrial mmWave Radar Family Technical Reference Manual* in [Section 6](#).

[Figure 2-1](#) and [Figure 2-2](#) show the device symbolization change from xWR1642 to xWR1843 on device part marking.

The left side device marking shows the xWR1642 silicon and the right side device marking shows the xWR1843 silicon. For more details on the device marking, see the device-specific Errata.

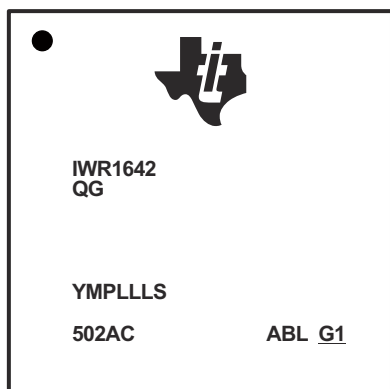


Figure 2-1. xWR1642 Device Marking

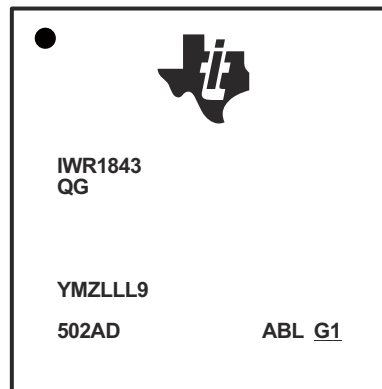


Figure 2-2. xWR1843 Device Marking

- [IWR1642 Device Errata](#)
- [AWR1642 Device Errata](#)
- [IWR1843 Device Errata](#)
- [AWR1843 Device Errata](#)

Table 2-1. Device Feature Comparison Table

No	Device Feature Differences	xWR1642	xWR1843	Hardware and Software Impact
1	Number of Transmit Channels	2	3 ⁽¹⁾	3rd Transmitter Antenna need to be designed. Update TX bitmap in chirpCfg
2	Maximum Sampling Rate	6.25 MHz complex	12.5 MHz complex	Higher IF bandwidth and Sampling rates are available on xWR1843
3	Max I/F (Intermediate Frequency)	5 MHz	10 MHz	
4	On-chip memory	1.5MB	2.0MB	Software can leverage the additional memory if needed.
5	Radar Accelerator	Not Applicable	Hardware accelerator for FFT, filtering, and CFAR processing	xWR1843 has flexibility of data processing on Hardware accelerator or DSP
6	Tx beam forming	No support	Supported	xWR1843 has phase shifters which supports the steerable beams. Note: Antennas need to be designed to support TX beam forming operation
7	MMWAVE-SDK support	SDK 2.1 (LTS) and above	SDK 3.3.0 and above	General software porting required compiling for xWR1843. For more information, see the Section 2.1.4 .

(1) Three Tx Simultaneous operation is supported only with 1-V LDO bypass and PA LDO disable mode. In this mode, the 1-V supply needs to be fed on the VOUT PA pin.

2.1.2 Hardware Migration Notes

2.1.2.1 Antenna Addition

From xWR1642 to xWR1843, the third antenna needs to be introduced. For more information, see the design file package that provides the antenna details. Detailed field of view and radiations can be found in the user's guides listed below.

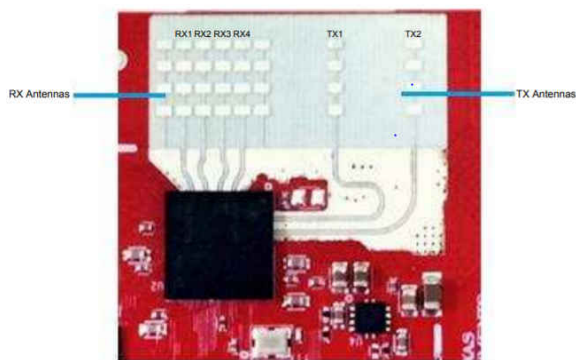


Figure 2-3. xWR1642 Antenna Image

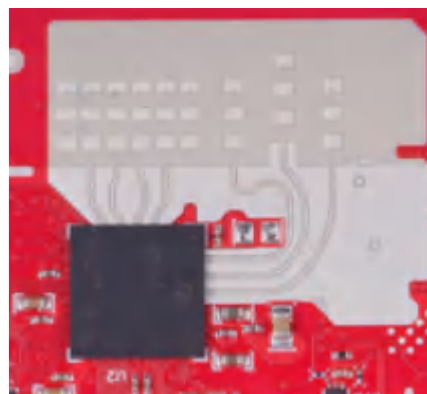


Figure 2-4. xWR1843 Antenna Image

- [xWR1642BOOST Layout and Design Files](#)
- [xWR1642 EVM \(xWR1642BOOST\) Single-Chip mmWave Sensing Solution User's Guide](#)
- [xWR1843BOOST Hardware Files](#)
- [xWR1843 Evaluation Module \(xWR1843BOOST\) Single-Chip mmWave Sensing Solution User's Guide](#)

2.1.3 Hardware Design Checklist

xWR1642 has the hardware design (schematic, Layout, bring-up/wakeup) checklist is available at <http://www.ti.com/lit/zip/swrr151> and for the xWR1843 hardware design (schematic, Layout, Bring up/wakeup) checklist is available at <http://www.ti.com/lit/zip/spracl2>.

2.1.4 Software Migration Notes

[Table 2-2](#) lists the changes required to port existing xWR1642 application code to xWR1843.

Note

The scope of the migration notes provided in this section is limited to migrating to MMWAVE-SDK 3.3.

When migrating existing xWR1843 applications to SDK releases beyond MMWAVE-SDK 3.3, you should follow the incremental migration instructions provided in the corresponding SDK release notes.

Table 2-2. xWR1642 to xWR1843 Software Migration

No	Summary	Components Impacted	Required Changes
1	MMWAVE-SDK 3.2.1 or above required for xWR1843 NOTE: It is recommended to use SDK 3.3.0 or above to include the latest API updates.	Makefile OR CCS projects	Application code must be re-compiled with MMWAVE-SDK 3.3.0 or above to run on xWR1843 Makefile: No change required if you are using SDK makefiles , as this is automatically handled in the SDK 3.3 environment setup script: C:\ti\mmwave_sdk_03_03_xx_xx\packages\scripts\windows\setenv.bat OR CCS Projects spec: If the application is compiled using CCS projectspecs, you need to update the products property in DSS and MSS projectspecs as shown below. <property name="products" value="com.ti.rtsc.SYSBIOS:6.73.01.01;com.ti.MMWAVE_SDK:3.3.0.03;"/> Example: For reference CCS projects for xWR1843, see the 18xx – mmWave SDK Demo available in: MMWAVE Industrial Toolbox .
2	Change device type	Makefile OR CCS projects	Makefile: For SDK makefile based build, set MMWAVE_SDK_DEVICE=iwr18xx/awr18xx in setenv.bat. C:\ti\mmwave_sdk_03_03_xx_xx\packages\scripts\windows\setenv.bat OR CCS Projects spec: If the application is compiled using CCS projectspecs, change the define SOC_XWR16XX to SOC_XWR18XX in DSS and MSS projectspecs. Example: For reference CCS projects for xWR1843, see the 18xx – mmWave SDK Demo available in: MMWAVE Industrial Toolbox .
3	Update RadarSS firmware file path	Makefile OR CCS projects (mss)	Need to use xWR18xx_radarss_rprc.bin in the metaimage generation step. Makefile: No change required if you are using SDK makefiles , as this is automatically handled in the SDK 3.3 environment setup script based on the MMWAVE_SDK_DEVICE variable. OR CCS Projects spec: If the application is compiled using CCS projectspecs, replace xwr16xx_radarss_rprc.bin with xWR18xx_radarss_rprc.bin in the metaimage generation steps (postbuild steps) Example: For reference CCS projects for xWR1843, see the 18xx – mmWave SDK Demo available in: MMWAVE Industrial Toolbox .

Table 2-2. xWR1642 to xWR1843 Software Migration (continued)

No	Summary	Components Impacted	Required Changes
4	Use xWR18xx platform linker command file	Makefile OR CCS projects	Makefile: No change required if you are using SDK makefiles, as this is automatically handled in the SDK 3.3 environment setup script based on the MMWAVE_SDK_DEVICE variable. OR CCS Projects: If the application is compiled using CCS projects, update the include paths for r4f_linker.cmd and c674x_linker.cmd to: COM_TI_MMWAVE_SDK_INSTALL_DIR/packages/ti/platform/xwr18xx/r4f_linker.cmd and COM_TI_MMWAVE_SDK_INSTALL_DIR/packages/ti/platform/xwr18xx/c674x_linker.cmd, respectively. Example: For reference CCS projects for xWR1843, see the 18xx – mmWave SDK Demo available in: MMWAVE Industrial Toolbox.
5	Include xWR18xx driver and CLI libs	Makefile OR CCS projects	Makefile: No change required if you are using SDK makefiles, as this is automatically handled in the SDK 3.3 environment setup script based on the MMWAVE_SDK_DEVICE variable. OR CCS Projects: If the application is compiled using CCS projects, update the linker include paths to select the *_xwr18xx.aer4f and *_xwr18xx.xe674 lib versions, for example: -llibsoc_xwr18xx.ae674, -llibsoc_xwr18xx.xe674, -llibcli_xwr18xx.aer4f
6	Update sensor front-end configuration parameters	CLI config file (.cfg) and/or source code	Update TX channel bitmap in chirpCfg CLI command and/or API to account for the 3rd TX. Example: For more information, see the sample config files in C:\ti\mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr18xx\mmw\profiles.
7	Replace 16xx SOC definitions with 18xx equivalents.	MSS/DSS source code	Replace SOC_XWR16XX_* definitions/macros in source code with corresponding SOC_XWR18XX_* definitions. For instance: Replace SOC_XWR16XX_MSS_ADCBUF_BASE_ADDRESS with SOC_XWR18XX_MSS_ADCBUF_BASE_ADDRESS, Similarly, in Pinmux configuration code: Replace SOC_XWR16XX_PINN5_PADBE with SOC_XWR18XX_PINN5_PADBE and so forth. The image below shows reference code difference between the SDK 16xx and 18xx mmw demos File:mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr18xx\mmw\mss\mss_main.c Code Snapshot: see Section 5.7.
8	API update for MMWave_open SDK 3.3 requires new parameter to be passed to MMWave_open	MSS/DSS start-up code	MMWave_open: Application must set the value of calibMonTimeUnit parameter before calling MMWave_open as shown below. The image below shows reference code updates in the SDK 68xx mmw demo (same applies to 18xx mmw demo) File:mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr68xx\mmw\mss\mss_main.c Code Snapshot: see Section 5.1.

Table 2-2. xWR1642 to xWR1843 Software Migration (continued)

No	Summary	Components Impacted	Required Changes
9	API update for ADCBuf_open SDK 3.3 requires new parameter to be passed to ADCBuf_open	MSS/DSS start-up code	ADCBUF_open: Application must set the value of socHandle in the ADCBufparams structure before calling ADCBUF_open as shown below. The image below shows reference code updates in the SDK 68xx mmw demo (same applies to 18xx mmw demo). File: mmwave_sdk_03_03_xx_xx\packages\ti\demo\utils\mmwdemo_adccconfig.c Code Snapshot: see Section 5.2 .
10	API update for CANFD_init SDK 3.3 requires new parameter to be passed to CANFD_init	Drivers	CANFD_init: Applications using CANFD driver must pass instance ID to the CANFD_init API as shown below. Only a value of 0 is supported at this time. The image below shows reference code updates in the SDK CANFD driver test (same for 18xx). File: mmwave_sdk_03_03_xx_xx\packages\ti\drivers\canfd\test\xwr618xx\main.c Code Snapshot: see Section 5.3 .
11	General note on CLI configuration file	Sensor Configuration	For applications that re-use the mmWave demo framework, ensure that the configuration commands (profileCfg, chirpCfg, frameCfg, and so forth) follow the format provided in the sample configuration files provided in the mmw demo directory: C:\ti\mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr18xx\mmw\profiles. For more information, see the <i>Configuration File Format</i> section of the mmwave SDK User's Guide . See Section 6 .

3 xWR6843AoP ES2.0 Migration

This section provides migration guidance to port Hardware and software from the xWR6843AoP ES1.0 to the xWR6843AoP ES2.0 device. The information provided here is meant to cover the major changes for migrating to a particular MMWAVE-SDK release at the time of writing. For more information, see the *Migration* section in the [MMWAVE-SDK Release Notes](#).

3.1 Hardware Changes From xWR6843AoP ES1.0 to xWR6843AoP ES2.0

The changes described in this section are relevant when migrating xWR6843AoP ES1.0 hardware to xWR6843AoP ES2.0. [Figure 3-1](#) shows the device symbolization change from ES1.0 to ES2.0 on device part marking.

Left side device marking shows ES1.0 silicon and right side device marking shows ES2.0 silicon. For more details on the device marking, see the [xWR6843 Device Errata, Silicon Revisions 1. and 2.0](#).

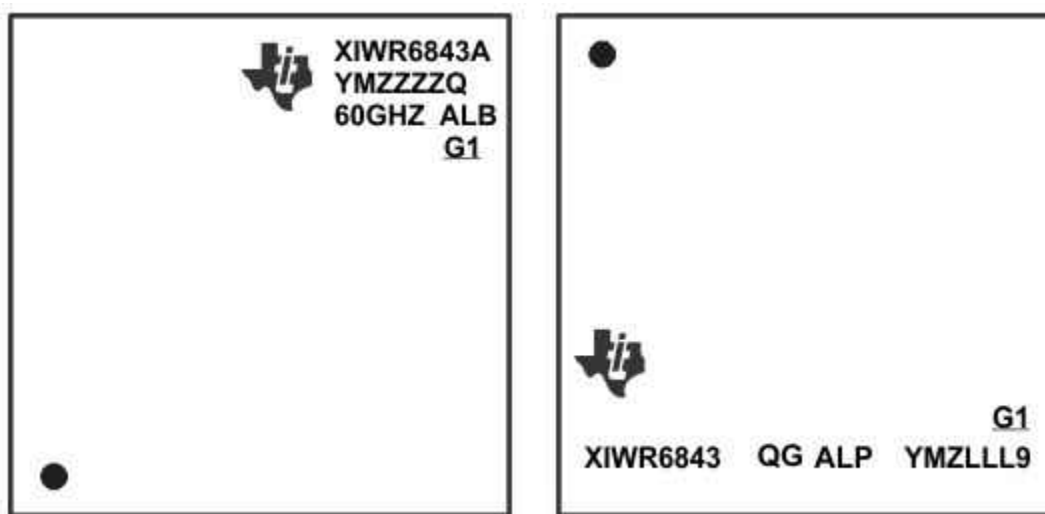


Figure 3-1. Silicon Device Marking Difference Between xWR6843AoP ES1.0 and ES2.0

Table 3-1. xWR6843AoP ES1.0 to xWR6843AoP ES2.0 Hardware Changes

No	Summary	xWR6843AoP ES1.0	xWR6843AoP ES2.0
1	QSPI interface speed has been improved. This enables faster boot loading, note that supported flashes are listed in the Flash Variants Supported by the mmWave Sensor .	Max 40 MHz	Max 80 MHz
2	Boot loader enhancement has been made. This allows faster boot and stability across devices	Boot loader code used to do the APLL calibration	Closed loop APLL calibration will be done by BSS
3	Tx beam scanning is introduced	No support	Supported
4	Memory compression (Depending upon the compression ratio of the RADAR data cube larger memory would be available for code and remaining data)	No support	Supported
5	Calibration is supported (This improves the performance and stability of the device across temperature)	No Calibration	Calibration supported
6	Clock gating at power-up and IP clock gating based on use-case, this should improve the power saving	No clock gating	Clock gated on unused peripherals. Device low level drivers un-gates the clock depending upon the peripheral used
7	RF Improvements –RX NF (Improved range and accuracy)	Baseline	Improved (Please refer to the data sheet for exact number)
8	RF Improvements –CLK PN (Improved accuracy)	Baseline	Improved (Please refer to the data sheet for exact number)

Table 3-1. xWR6843AoP ES1.0 to xWR6843AoP ES2.0 Hardware Changes (continued)

No	Summary	xWR6843AoP ES1.0	xWR6843AoP ES2.0
9	Package change	Baseline	Improved package (Please refer to the data sheet for detailed package information)
10	Changes in Antenna virtual Array	Baseline	Improvement in package routing caused changes in the antenna elements, hence there is change in virtual antenna array between ES1 and ES2.0. See Table 3-2

3.2 Software Migration From xWR6843AoP ES1.0 to xWR6843AoP ES2.0

The changes described in this section are relevant for migrating the xWR6843AoP ES1.0 software based on the SDK 3.2.0.6 to xWR6843AoP ES2.0 and SDK 3.4.

Besides the addition of the Antenna on Package and a different antenna pattern, xWR6843AoP ES2.0 re-uses the same silicon. Hence software migration from xWR6843AoP ES1.0 to xWR6843AoP ES2.0 broadly includes the following steps in order:

1. Initial migration of software to xWR6843ES2.0 (from MMWAVE-SDK 3.2.0.6 to MMWAVE-SDK 3.4). (Referred to below as **Platform Software Updates**)
2. Angle of Arrival Processing updates for the updated antenna pattern on xWR6843AoP ES2.0. (Referred to below as **AoA Software Updates**)

Note

MMWAVE-SDK 3.4.0 is the first baseline SDK release for xWR6843AoP ES2.0 device and the scope of migration notes provided in this section is limited to migrating to MMWAVE-SDK 3.4.0

When migrating existing xWR6843 AoP ES2.0 applications to SDK releases beyond MMWAVE SDK 3.4, you should follow the incremental migration instructions provided in the corresponding SDK release notes.

3.2.1 xWR6843AoP ES2.0 - Platform Software Updates

Table 3-2. xWR6843AoP ES2.0 Software - Platform Updates

No	Summary	Components Impacted	Required Changes
1	MMWAVE-SDK 3.4.0 or above required for xWR6843AoP ES2.0	Makefile OR CCS projects	Application code must be re-compiled with MMWAVE-SDK 3.4.0 or above to run on xWR6843AoP ES2.0 as prior SDK versions are not compatible with ES2.0. Conversely, SDK 3.4.0 is not compatible with xWR6843AoP ES1.0 devices. Makefile: No change required if you are using SDK makefiles, as this is automatically handled in the SDK 3.4 environment setup script: C:\ti\mmwave_sdk_03_04_xx_xx\packages\script\windows\setenv.bat OR CCS Projects spec: If the application is compiled using CCS projectspecs, you need to update the products property in DSS and MSS projectspecs as shown below. <property name="products" value="com.ti.rtsc.SYSBIOS:6.73.01.01;com.ti.MMWAVE_SDK:3.4.0.03;"/> Example: For reference CCS projects for xWR6843AoP ES2.0, see the 68xx AoP – mmWave SDK Demo available in MMWAVE Industrial Toolbox.
2	Change the value of SHMEM_ALLOC parameter in MetalImage (flashable) binary generation step.	Makefile OR CCS projects (mss).	The value of SHMEM_ALLOC parameter should be set to 0x00000006 for ES2.0 (it was 0x02000006 for ES1.0 device). Makefile: No change required if you are using SDK makefiles build, as this is automatically handled in the SDK 3.4 device specific makefiles. OR CCS Projects spec: If the application is compiled using CCS projectspecs, update the postBuildStep in MSS projectspec to replace the value 0x02000006 with 0x00000006. Example: For reference CCS projects for xWR6843AoP ES2.0, see the 68xx AoP – mmWave SDK Demo available in MMWAVE Industrial Toolbox.

Table 3-2. xWR6843AoP ES2.0 Software - Platform Updates (continued)

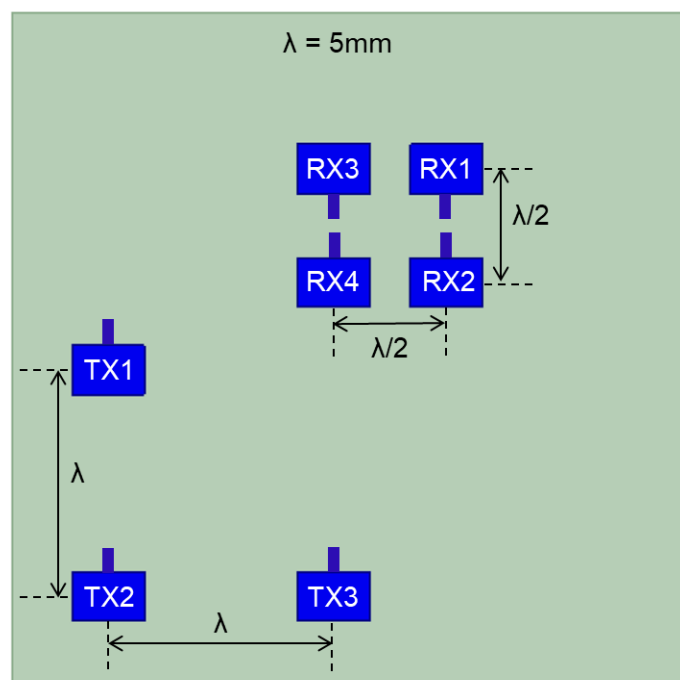
No	Summary	Components Impacted	Required Changes
3	Update RadarSS firmware file name	Makefile OR CCS projects (mss)	The RadarSS binary for xwr6xxx devices is now called xwr6xxx_radarss_rprc.bin instead of iwr6xxx_radarss_rprc.bin. Makefile: No change required if you are using SDK makefiles , as this is automatically handled in the SDK 3.4 environment setup script based on the MMWAVE_SDK_DEVICE variable. OR CCS Projects spec: If the application is compiled using CCS projectspecs, replace iwr6xxx_radarss_rprc.bin with xwr6xxx_radarss_rprc.bin in the metaimage generation steps (postbuild steps) Example: For reference CCS projects for xWR6843AoP ES2.0, see the 68xx AoP – mmWave SDK Demo available in MMWAVE Industrial Toolbox .
4	API update for MMWave_open SDK 3.3 and above requires a new parameter to be passed to MMWave_open	MSS/DSS start-up code	MMWave_open: Application must set the value of calibMonTimeUnit parameter before calling MMWave_open as shown below. The image below shows reference code updates in the SDK 68xx mmw demo File: mmwave_sdk_03_04_xx_xx\packages\ti\demo\xwr68xx\mmw\mss\mss_main.c Code Snapshot: see Section 5.1
5	API update for ADCBuf_open SDK 3.3 and above requires a new parameter to be passed to ADCBuf_open	MSS/DSS start-up code	ADCBUF_open: Application must set the value of socHandle in the ADCBufparams structure before calling ADCBUF_open as shown below. The image below shows reference code updates in the SDK 68xx mmw demo. File: mmwave_sdk_03_04_xx_xx\packages\ti\demo\utils\mmwdemo_adccconfig.c Code Snapshot: see Section 5.2
6	API update for CANFD_init SDK 3.3 and above requires new parameter to be passed to CANFD_init	Drivers	CANFD_init: Applications using CANFD driver must pass instance ID to the CANFD_init API as shown below. Only a value of 0 is supported at this time. The image below shows reference code updates in the SDK CANFD driver test. File: mmwave_sdk_03_04_xx_xx\packages\ti\drivers\canfd\test\xwr68xx\main.c Code Snapshot: see Section 5.3
7	SDK 3.3 and above removes support for Bus error interrupt from the DMA driver for xWR6843 ES2 as that interrupt is not hooked up to the device.	Drivers	Application would get an error code back from the xwr68xx driver if DMA_enable Interrupt API is called for DMA_IntType_BER. You can either remove the call to the above API or ignore the error; however you should review the DMA usage to make sure there is no invalid memory access via MSS DMA engine.
8	General note on CLI configuration file	Sensor Configuration	For applications that re-use the mmWave demo/CLI framework, ensure that the configuration commands (for example, profileCfg, chirpCfg, frameCfg, and so forth) follow the format provided in sample configuration files provided in the mmw demo directory: C:\ti\mmwave_sdk_03_04_xx_xx\packages\ti\demo\xwr64xx\mmw\profiles. for more details, see the <i>Configuration File Format</i> section in the mmwave SDK User's Guide . Section 6

Table 3-2. xWR6843AoP ES2.0 Software - Platform Updates (continued)

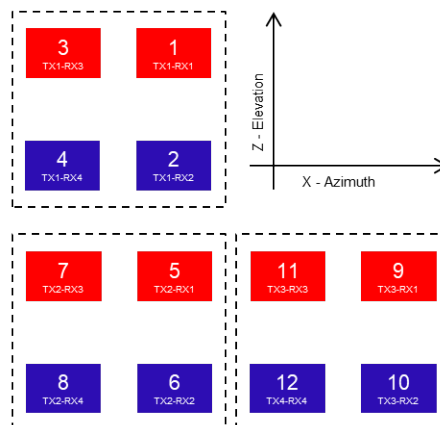
No	Summary	Components Impacted	Required Changes
9	BSS clock un-gate required in Secondary bootloader	Secondary Bootloader	Note: This update is not related to the main application. It is needed only if you are using a custom secondary bootloader in your system. The Secondary Bootloader must ungate BSS clock using SOC gate/ungate API before downloading image to RadarSS/BSS memory as shown below. The image below shows reference code updates in the SDK secondary bootloader example. File: C:\ti\mmwave_sdk_03_04_xx_xx\packages\ti\utils\sb\platform\sb_xwr68xx.c Code Snapshot: see Section 5.4
10	SDK 3.4 mmWave layer enables all valid init time and runtime calibrations for xwr6xxx devices	MSS/DSS start-up code	Application should pass valid values for freqLimitLow and freqLimitHigh in mmWave_Open API and can now enable periodic calibrations in mmWave_Start API The image below shows reference code updates in the SDK 68xx mmw demo. File: mmwave_sdk_03_04_00_03\packages\ti\demo\xwr68xx\mmw\mss\mss_main.c Code Snapshot: see Section 5.8
11	Object detection DPC accepts antenna geometry to enable wider configurations of Tx/Rx antennas	DPCconfiguration	This field is mandatory only for HWA-based Object detection DPC when compiled to use the new AoA 2D algorithm (in the xwr64xx AoP mmw demo). For DSP-based DPC and for HWA-based DPC that uses standard AoA DPU, this field is unused. The image below shows the reference code in the SDK 64xx mmw demo. File: mmwave_sdk_03_04_00_03\packages\ti\demo\xwr64xx\mmw\main.c Code Snapshot: see Section 5.14
12	Object Detection HWA DPC now accepts Range FFT Scaling Parameters	DPC configuration	Range HWA-based DPU and Object detection HWA-based DPCs now allow you to set the scaling values for butterfly stages and converting from internal 24-bit to 16-bit output The image below shows the reference code in the SDK 64xx mmw demo. File: mmwave_sdk_03_04_00_03\packages\ti\demo\xwr64xx\mmw\main.c Code Snapshot: see Section 5.9
13	Objectdetection Range HWA DPC now allows user to specify the radar cube format	DPC Configuration	ObjDetRangeHWA DPC allows user to specify the radar cube format to allow flexibility in integrating various DSP based algorithms/processing chains Note: mmW demos support only DPIF_RADARCUBE_FORMAT_ The image below shows the reference code in the SDK 68xx mmw demo. File: mmwave_sdk_03_04_00_03\packages\ti\demo\xwr68xx\mmw\mss\mss_main.c Code Snapshot: see Section 5.10
14	Updates related to saving/restoring device calibration parameters (Phase shift calibration parameters)	For more details on this and other calibration related updates, see the MMWAVE-SDK 3.4.0 release notes in the Migration Notes .	

3.2.2 xWR6843AoP ES2.0 - AoA Software Updates

Figure 3-2 and Figure 3-3 compare the antenna geometries of xWR6843AOP ES1.0 and xWR6843AOP ES2.0.

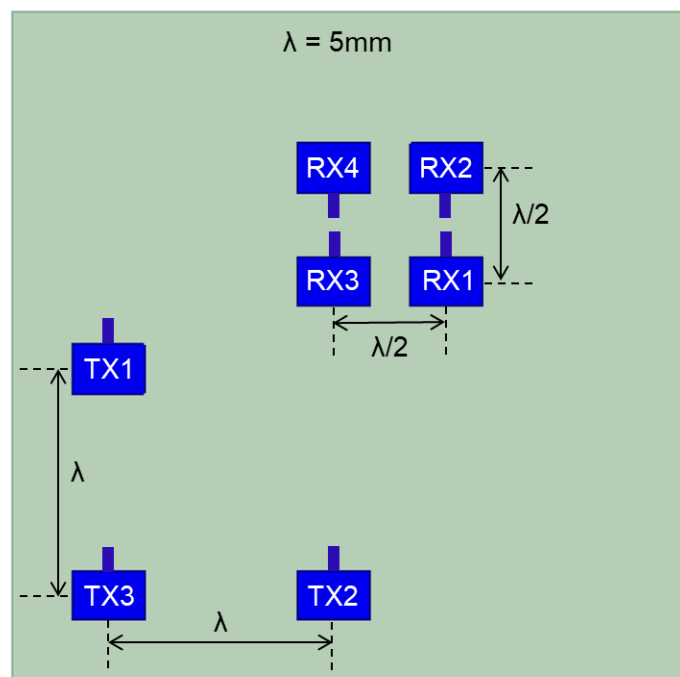


MIMO Virtual
Antenna Array

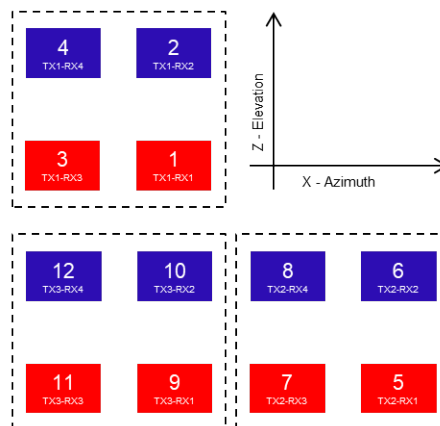


RX1 and RX3 are 180° out of phase with respect to RX2 and RX4. Because of this, a 180° phase inversion needs to be applied in software processing for the corresponding virtual RX channels (highlighted in Red)

Figure 3-2. xWR6843AoP ES1.0 Antenna Geometry and Resulting MIMO Virtual Antenna Array



MIMO Virtual
Antenna Array



RX1 and RX3 are 180° out of phase with respect to RX2 and RX4, similar to ES1. Because of this, a 180° phase inversion needs to be applied in software processing for the corresponding virtual RX channels (highlighted in Red)

Figure 3-3. xWR6843AoP ES2.0 Antenna Geometry and Resulting MIMO Virtual Antenna Array

The key antenna updates in xWR6843AoP ES2, as shown above are:

- **RX Antennas:** RX1 and RX2 are swapped on xWR6843AoP ES2. Similarly RX3 and RX4 are swapped
- **TX Antennas:** TX2 and TX3 are swapped on xWR6843AoP ES2.
- **Line Feed:** The RX line feeds on xWR6843AoP ES2 are same as on ES1 i.e. RX1 and RX2 are fed from opposite ends, which results in a 180° phase difference between RX1 and RX2. Similarly, RX3 and RX4 are

out of phase by 180°. To compensate for the opposite line feeds, a 180° phase inversion needs to be applied in software processing for the corresponding virtual channels as shown in Figure 3-3.

MMWAVE-SDK 3.2.0.6 and MMWAVE-SDK 3.4 include the AoA2dProc DPU which performs Angle of Arrival processing for the xWR6843 AoP antenna array using the Hardware Accelerator. The AoA2dProc DPU (Datapath Processing Unit) is used in the xWR64xx AoP mmw demo for angle of arrival processing.

To understand the AoA updates needed for xWR6843AoP ES2, it is recommended to understand the antenna geometry concept defined in AoA2dProc DPU.

1. Navigate to C:\ti\mmwave_sdk_03_04_xx_xx\docs and open the file mmwave_sdk_module_documentation.html in a browser.
2. Click on the AoA using 2D FFT method link as highlighted in the picture below:

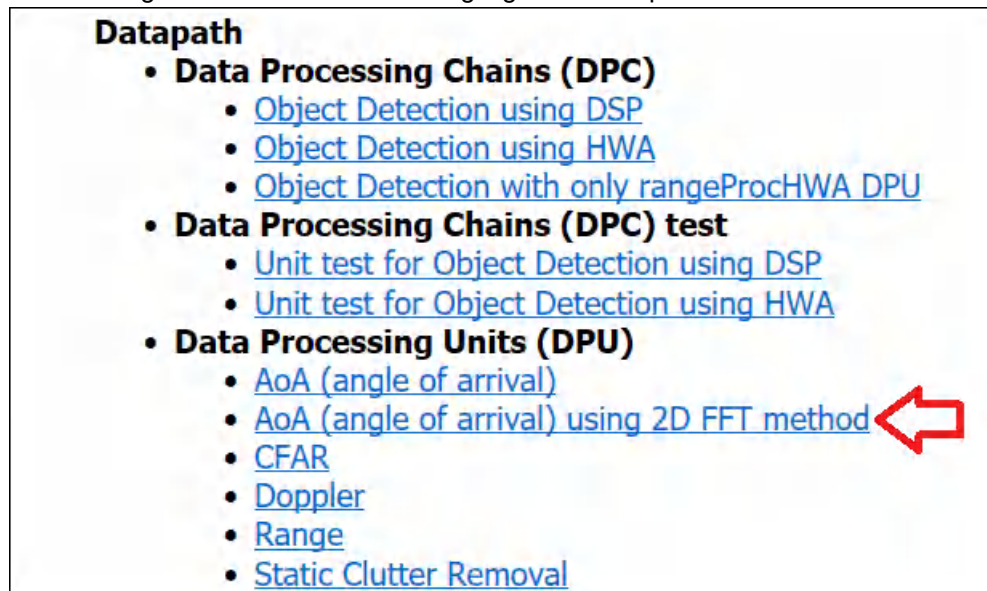


Figure 3-4. AoA2dProc HTML Documentation

3. Scroll down to the section named Antenna Geometry Definition, which explains how the generic antenna geometry structure is defined and used by the HWA AoA2dProc DPU code. The antenna geometry for a specific antenna (for example, xWR6843AoP ES2.0) is defined in the corresponding C structure in mmwave_sdk_03_04_xx_xx\packages\ti\board\antenna_geometry.c.

The image below shows the antenna geometry structure update for xWR6843AoP ES2.0 as compared to xWR6843AoP ES1.0 in MMWAVE-SDK 3.2.0.6.

Code Snapshot: see [Section 5.13](#)

The antenna geometry structure is passed to the Object Detection DPC during initialization in mmwave_sdk_03_04_xx_xx\packages\ti\demo\xwr64xx\mmw\main.c

Code Snapshot: see [Section 5.14](#)

RX Channel Phase Compensation: To compensate for the opposite line feeds as shown in [Section 5.12](#), a 180° phase inversion is applied to the corresponding RX channels (including virtual channels) using the compRangeBiasAndRxChanPhase CLI command available in the mmw demo.

Figure 3-5, from the MMWAVE-SDK user's guide, explains the structure of this command.

compRangeBiasAndRxChanPhase	Command for datapath to compensate for bias in the range estimation and receive channel gain and phase imperfections. Refer to the procedure mentioned here The values in this command can be changed between sensorStop and sensorStart and even when the sensor is running. This is a mandatory command.	<rangeBias> Compensation for range estimation bias in meters <Re(0,0)> <Im(0,0)> <Re(0,1)> <Im(0,1)> ... <Re(0,R-1)> <Im(0,R-1)> <Re(1,0)> <Im(1,0)> ... <Re(T-1,R-1)> <Im(T-1,R-1)> Set of Complex value representing compensation for virtual Rx channel phase bias in Q15 format. Pairs of I and Q should be provided for all Tx and Rx antennas in the device	supported For xwr1843, xwr6843 and xwr6443 demos: 12 pairs of values should be provided here since the device has 4 Rx and 3 Tx (total of 12 virtual antennas). Note the sign reversal required for phase compensation coefficients in xwr6443 demo running on IWR6843AOP device. For xwr1642 demo: 8 pairs of values should be provided here since the device has 4 Rx and 2 Tx (total of 8 virtual antennas)
-----------------------------	---	--	---

Figure 3-5. RX Channel Phase Compensation: CompRangeBiasAndRxChanPhase CLI Command

To understand the CompRangeBiasAndRxChanPhase values configured in the example AoP profile configuration provided in MMWAVE-SDK, see [Section 5.15](#).

4 Helpful Resources

The following resources provide example source code, makefile and CCS projects for the xWR6843 ES2.0 and the xWR1843 devices.

Resource Name	File-System Path / Web URL	Content Reference
MMWAVE-SDK 3.3 mmw demo	68xx - C:\ti\mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr68xx\mmw 18xx - C:\ti\mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr18xx\mmw	Source code, Makefiles, Configuration files (.cfg)
MMWAVE-SDK 3.4 mmw demo	68xx - C:\ti\mmwave_sdk_03_04_xx_xx\packages\ti\demo\xwr68xx\mmw 64/68xxAoP C:\ti\mmwave_sdk_03_04_xx_xx\packages\ti\demo\xwr64xx\mmw	
MMWAVE Industrial Toolbox	MMWAVE Industrial Toolbox 68xx ISK – mmWave SDK Demo – DSP Version 64/68xx AoP - mmWave SDK Demo 68xx AoP 18xx – mmWave SDK Demo And various other demos included in Industrial Toolbox	Reference CCS Projects specs for mmWave SDK mmw demos and other application specific demos.

5 Code Snapshots

This section provides code snapshots for the migrations notes presented in the previous sections.

5.1 SDK 3.3 API Change for MMWave_open

MMWAVE-SDK 3.2.1 vs MMWAVE-SDK 3.3.0

File: mmwave_sdk_03_03_00_0x\packages\ti\demo\xwr68xx\mmw\mss_main.c

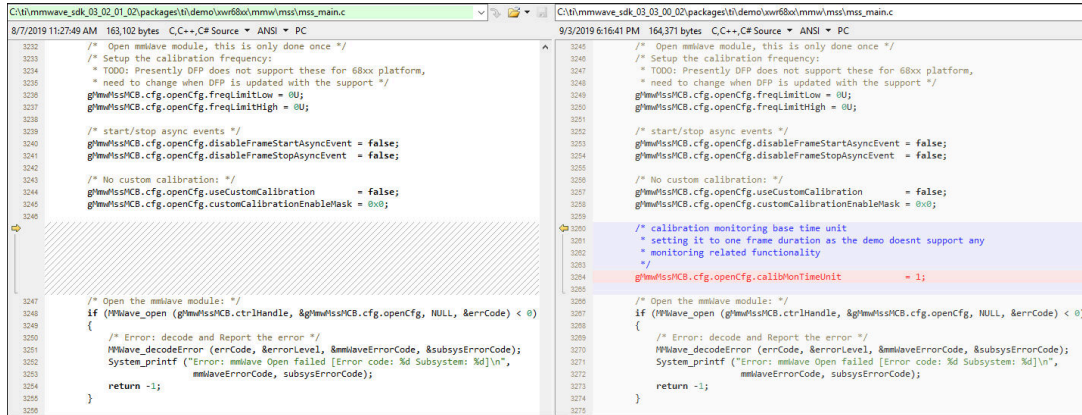


Figure 5-1. SDK 3.3 API Change for MMWave_open

5.2 SDK 3.3 API Change for ADCBuf_open

MMWAVE-SDK 3.2.1 vs MMWAVE-SDK 3.3.0

File: mmwave_sdk_03_03_00_0x\packages\ti\demo\xwr68xx\mmw\mss_main.c

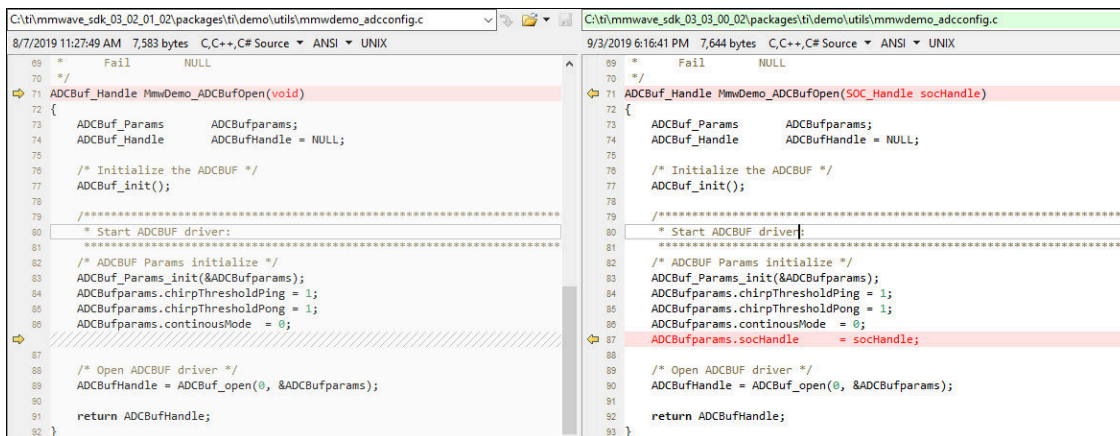


Figure 5-2. SDK 3.3 API Change for ADCBuf_open

5.3 SDK 3.3 API Change for CANFD_init

MMWAVE-SDK 3.2.1 vs MMWAVE-SDK 3.3.0

File: mmwave_sdk_03_03_00_0x\packages\ti\drivers\canfd\test\xwr68xx\main.c

File: C:\ti\mmwave_sdk_03_01_02\packages\ti\drivers\canfd\test\xwr68xx\main.c	File: C:\ti\mmwave_sdk_03_03_00_02\packages\ti\drivers\canfd\test\xwr68xx\main.c
<pre> 394 395 static int32_t mcanLoopbackTest() 396 { 397 CANFD_Handle canHandle; 398 CANFD_MsgObjHandle txMsgObjHandle; 399 CANFD_MsgObjHandle rxMsgObjHandle; 400 int32_t retVal = 0; 401 int32_t errCode = 0; 402 CANFD_OptionTLV optionTLV; 403 uint8_t value; 404 CANFD_MCANInitParams mcanCfgParams; 405 CANFD_MCANBitTimingParams mcanBitTimingParams; 406 CANFD_MCANMsgObjCfgParams txMsgObjectParams; 407 CANFD_MCANMsgObjCfgParams rxMsgObjectParams; 408 CANFD_MCANLoopbackCfgParams mcanLoopbackParams; 409 CANFD_MCANMsgObjectStats msgObjStats; 410 411 gTxDoneFlag = 0; 412 413 MCANAppInitParams (&mcanCfgParams); 414 415 /* Initialize the CANFD driver */ 416 canHandle = CANFD_init(&mcanCfgParams, &errCode); 417 if (canHandle == NULL) 418 { 419 System_printf ("Error: CANFD Module Initialization failed [Error 420 return -1; 421 } </pre>	<pre> 397 static int32_t mcanLoopbackTest() 398 { 399 CANFD_Handle canHandle; 400 CANFD_MsgObjHandle txMsgObjHandle; 401 CANFD_MsgObjHandle rxMsgObjHandle; 402 int32_t retVal = 0; 403 int32_t errCode = 0; 404 CANFD_OptionTLV optionTLV; 405 uint8_t value; 406 CANFD_MCANInitParams mcanCfgParams; 407 CANFD_MCANBitTimingParams mcanBitTimingParams; 408 CANFD_MCANMsgObjCfgParams txMsgObjectParams; 409 CANFD_MCANMsgObjCfgParams rxMsgObjectParams; 410 CANFD_MCANLoopbackCfgParams mcanLoopbackParams; 411 CANFD_MCANMsgObjectStats msgObjStats; 412 413 gTxDoneFlag = 0; 414 415 MCANAppInitParams (&mcanCfgParams); 416 417 /* Initialize the CANFD driver */ 418 canHandle = CANFD_init(gInstanceId, &mcanCfgParams, &errCode); 419 if (canHandle == NULL) 420 { 421 System_printf ("Error: CANFD Module Initialization failed [Error 422 return -1; 423 } </pre>

Figure 5-3. SDK 3.3 API Change for CANFD_init

5.4 SDK 3.3 68xx Secondary Bootloader Update

MMWAVE-SDK 3.2.1 vs MMWAVE-SDK 3.3.0

File: mmwave_sdk_03_03_00_02\packages\ti\utils\sbl\platform\sbl_xwr68xx.c

File: C:\ti\mmwave_sdk_03_01_02\packages\ti\utils\sbl\platform\sbl_xwr68xx.c	File: C:\ti\mmwave_sdk_03_03_00_02\packages\ti\utils\sbl\platform\sbl_xwr68xx.c
<pre> 432 { 433 offset = (uint32_t)SBL_BSS_SHARED_MEM_TCMB_OFFSET; 434 } 435 else if ((sectionPtr + sectionLen) <= SBL_BSS_SECTION_END_ADDR 436 { 437 offset = (uint32_t)SBL_BSS_SHARED_MEM_OFFSET; 438 } 439 else 440 { 441 offset = 0U; 442 gSblMCB.errorStatus = SBL_RPRC_PARSER_BSS_FILE_OFFSET_MIS 443 } 444 445 /* Configure the MPU settings for BSS section */ 446 if (gSblMCB.bssMpuInit == 0) 447 { 448 gSblMCB.bssMpuInit = 1U; 449 } 450 451 /* Enable the regions */ 452 SBL_mpuConfigBSS(true); 453 } </pre>	<pre> 433 { 434 offset = (uint32_t)SBL_BSS_SHARED_MEM_TCMB_OFFSET; 435 } 436 else if ((sectionPtr + sectionLen) <= SBL_BSS_SECTION_END_ADDRESS) 437 { 438 offset = (uint32_t)SBL_BSS_SHARED_MEM_OFFSET; 439 } 440 else 441 { 442 offset = 0U; 443 gSblMCB.errorStatus = SBL_RPRC_PARSER_BSS_FILE_OFFSET_MISMATCH; 444 } 445 446 /* Configure the MPU settings for BSS section */ 447 if (gSblMCB.bssClockMpuInit == 0) 448 { 449 gSblMCB.bssClockMpuInit = 1U; 450 } 451 /* ungate clock */ 452 SOC_ungateClock(gSblMCB.socHandle, SOC_MODULE_BSS, &errCode); 453 454 /* Enable the regions */ 455 SBL_mpuConfigBSS(true); 456 } </pre>

Figure 5-4. SDK 3.3 68xx Secondary Bootloader Update

5.5 SDK 3.3 16xx vs 68xx: Calibration Frequency Update

MMWAVE-SDK 3.3.0 mmw demo (16xx vs 68xx)

File: mmwave_sdk_03_03_00_0x\packages\ti\demo\xwr68xx\mmw\mss_main.c

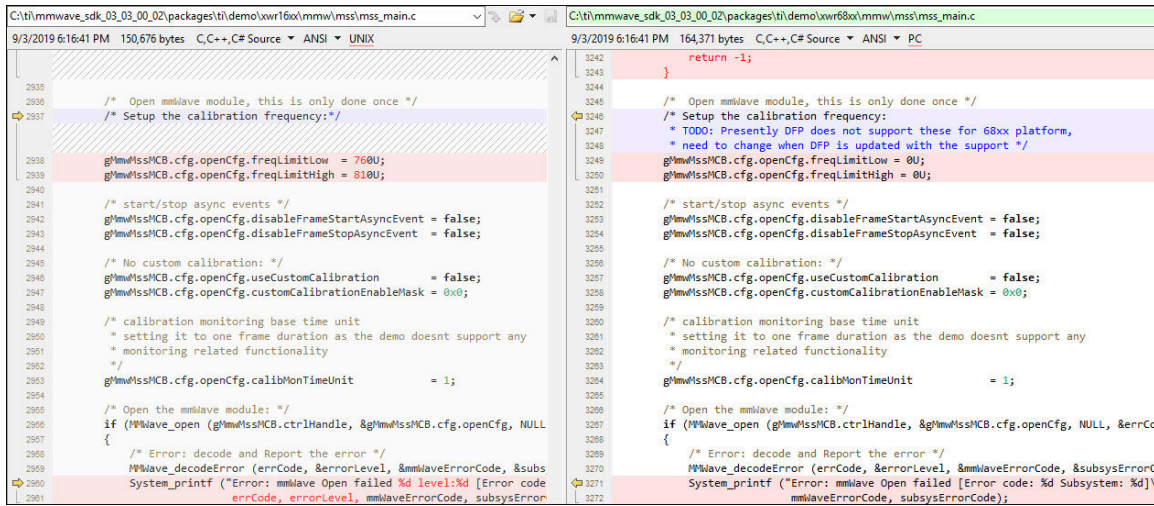


Figure 5-5. SDK 3.3 16xx vs 68xx: Calibration Frequency Update

5.6 SDK 3.3 16xx vs 68xx: SoC Definition Updates

MMWAVE-SDK 3.3.0 mmw demo (16xx vs 68xx)

File: mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr68xx\mmw\mss_main.c

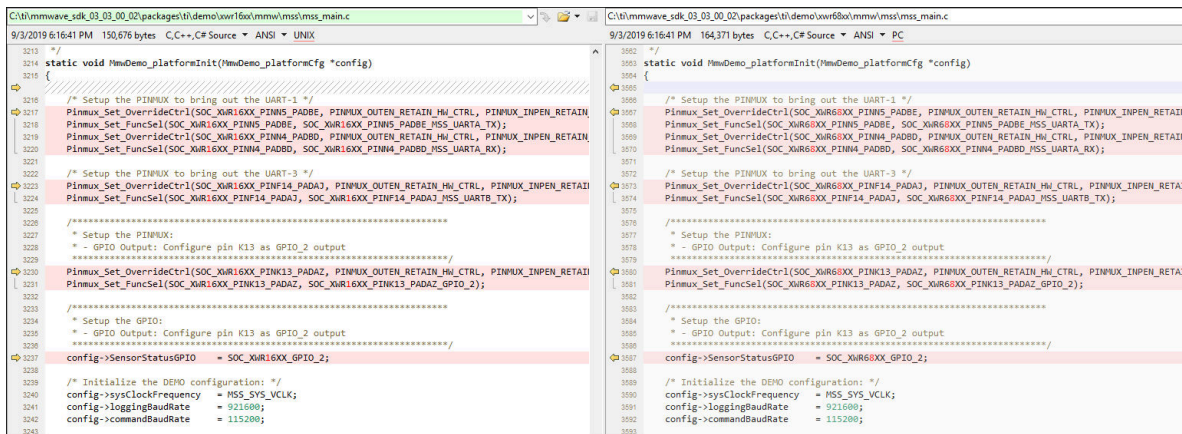


Figure 5-6. SDK 3.3 16xx vs 68xx: SoC Definition Updates

5.7 SDK 3.3 16xx vs 18xx: SoC Definition Updates

MMWAVE-SDK 3.3.0 mmw demo (16xx vs 18xx)

File: mmwave_sdk_03_03_xx_xx\packages\ti\demo\xwr18xx\mmw\mss_main.c

Figure 5-7. SDK 3.3 16xx vs 18xx: SoC Definition Updates

5.8 SDK 3.4 xWR68xx Calibration Frequency Update

MMWAVE-SDK 3.3 vs MMWAVE-SDK 3.4

File: mmwave_sdk_03_04_00_0x\packages\ti\demo\xwr68xx\mmw\mss_main.c

Figure 5-8. SDK 3.4 xWR68xx Calibration Frequency Update

5.9 SDK 3.4 Object Detect HWA DPC Range FFT Scaling

MMWAVE-SDK 3.3 vs MMWAVE-SDK 3.4

File: mmwave_sdk_03_04_00_0x\packages\ti\demo\xwr64xx\mmw\main.c

C:\ti\mmwave_sdk_03_03_00_03\packages\ti\demo\xwr64xx\mmw\main.c	C:\ti\mmwave_sdk_03_04_00_03\packages\ti\demo\xwr64xx\mmw\main.c
9/16/2019 1:01:15 PM 132,920 bytes C,C++,C# Source ANSI UNIX	3/30/2020 6:14:33 PM 137,509 bytes C,C++,C# Source ANSI UNIX
<pre> 1667 staticCfg->numVirtualAntAzim = RfparserOutParams.numVirtualAntAzim; 1668 staticCfg->numVirtualAntElev = RfparserOutParams.numVirtualAntElev; 1669 staticCfg->numVirtualAntennas = RfparserOutParams.numVirtualAntennas; 1670 staticCfg->rangeStep = RfparserOutParams.rangeStep; </pre>	<pre> 1705 staticCfg->numVirtualAntAzim = RfparserOutParams.numVirtualAntAzim; 1706 staticCfg->numVirtualAntElev = RfparserOutParams.numVirtualAntElev; 1707 staticCfg->numVirtualAntennas = RfparserOutParams.numVirtualAntennas; 1708 staticCfg->rangeStep = RfparserOutParams.rangeStep; 1709 1710 /* Current 64xx/68xx SOC has higher receive level as compared to 18xx a 1711 * fftOutputDivShift to avoid overflow when converting from 24-bit to 1 1712 * TODO: Future RadarSS firmware should be evaluated to assess if these 1713 */ 1714 if (RfparserOutParams.numRangeBins >= 1022) 1715 { 1716 staticCfg->rangeFFTtuning.fftOutputDivShift = 1; 1717 /* scale only 2 stages */ 1718 staticCfg->rangeFFTtuning.numLastButterflyStagesToScale = 2; 1719 } 1720 else if (RfparserOutParams.numRangeBins==512) 1721 { 1722 staticCfg->rangeFFTtuning.fftOutputDivShift = 2; 1723 /* scale last stage */ 1724 staticCfg->rangeFFTtuning.numLastButterflyStagesToScale = 1; 1725 } 1726 else 1727 { 1728 staticCfg->rangeFFTtuning.fftOutputDivShift = 3; 1729 /* no scaling needed as ADC data is 16-bit and we have 8 bits to grow 1730 staticCfg->rangeFFTtuning.numLastButterflyStagesToScale = 0; 1731 } 1732 1733 for (i = 0; i < RfparserOutParams.numRxAntennas; i++) 1734 { </pre>

Figure 5-9. SDK 3.4 Object Detection DPC FFT Range Scaling Configuration

5.10 SDK 3.4 Object Detect Range HWA DPC Radar Cube Format

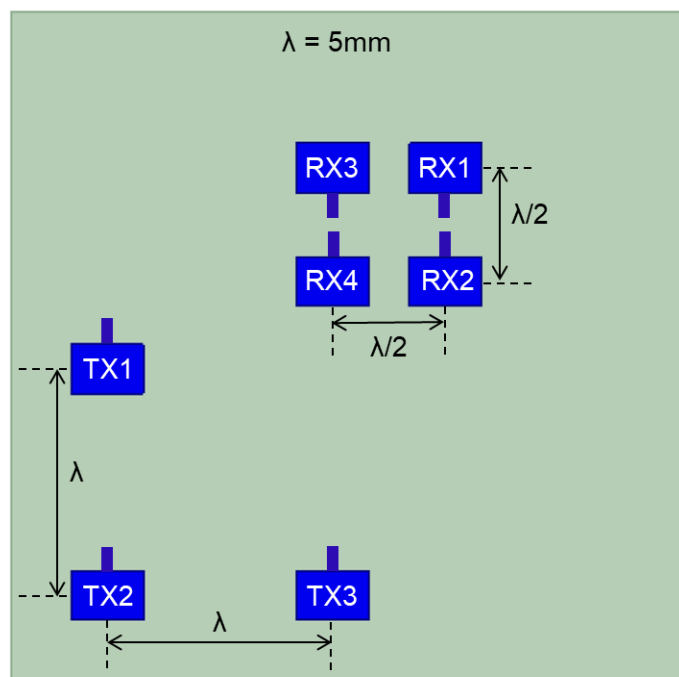
MMWAVE-SDK 3.3 vs MMWAVE-SDK 3.4

File: mmwave_sdk_03_04_00_0x\packages\ti\demo\xwr68xx\mmw\mss\mss_main.c

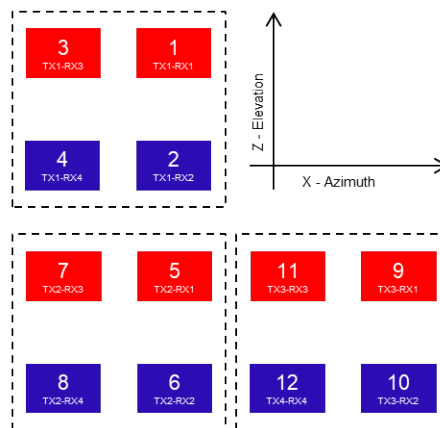
C:\ti\mmwave_sdk_03_03_00_03\packages\ti\demo\xwr68xx\mmw\mss\mss_main.c	C:\ti\mmwave_sdk_03_04_00_03\packages\ti\demo\xwr68xx\mmw\mss\mss_main.c
9/16/2019 1:01:15 PM 164,371 bytes C,C++,C# Source ANSI PC	3/30/2020 6:14:33 PM 167,431 bytes C,C++,C# Source ANSI PC
<pre> 2078 staticCfg->numRangeBins = RfparserOutParams.numRangeBins; 2079 staticCfg->numTxAntennas = RfparserOutParams.numTxAntennas; 2080 staticCfg->numVirtualAntennas = RfparserOutParams.numVirtualAntennas; 2081 </pre>	<pre> 2110 staticCfg->numRangeBins = RfparserOutParams.numRangeBins; 2111 staticCfg->numTxAntennas = RfparserOutParams.numTxAntennas; 2112 staticCfg->numVirtualAntennas = RfparserOutParams.numVirtualAntennas; 2113 2114 /* Current 68xx SOC has higher receive level as compared to 18xx and hence usi 2115 * fftOutputDivShift to avoid overflow when converting from 24-bit to 16-bit 2116 * TODO: Future RadarSS firmware should be evaluated to assess if these settin 2117 */ 2118 if (RfparserOutParams.numRangeBins >= 1022) 2119 { 2120 staticCfg->rangeFFTtuning.fftOutputDivShift = 1; 2121 /* scale only 2 stages */ 2122 staticCfg->rangeFFTtuning.numLastButterflyStagesToScale = 2; 2123 } 2124 else if (RfparserOutParams.numRangeBins==512) 2125 { 2126 staticCfg->rangeFFTtuning.fftOutputDivShift = 2; 2127 /* scale last stage */ 2128 staticCfg->rangeFFTtuning.numLastButterflyStagesToScale = 1; 2129 } 2130 else 2131 { 2132 staticCfg->rangeFFTtuning.fftOutputDivShift = 3; 2133 /* no scaling needed as ADC data is 16-bit and we have 8 bits to grow */ 2134 staticCfg->rangeFFTtuning.numLastButterflyStagesToScale = 0; 2135 } 2136 2137 /* objectdetection DSP DPC needs radacube in format DPIF_RADARCUBE_FORMAT_1 */ 2138 staticCfg->radarCubeFormat = DPIF_RADARCUBE_FORMAT_1; 2139 2140 /* Fill dynamic configuration for the sub-frame */ 2141 objDetPreStartR4fCfg.dynCfg = subFrameCfg->objDetDynCfg.r4fDynCfg; </pre>

Figure 5-10. SDK 3.4 Object Detect Range HWA DPC FFT Radar Cube Format

5.11 xWR6843AoP ES1.0 Antenna Geometry



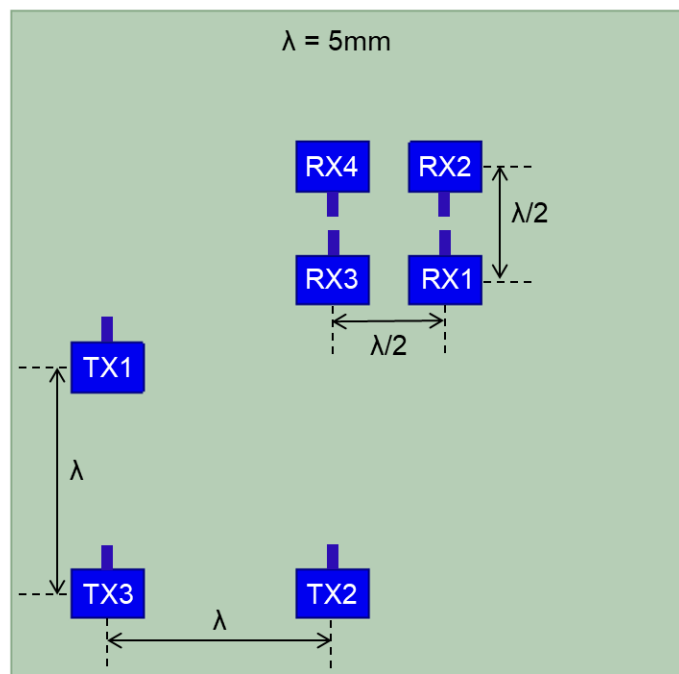
MIMO Virtual
Antenna Array



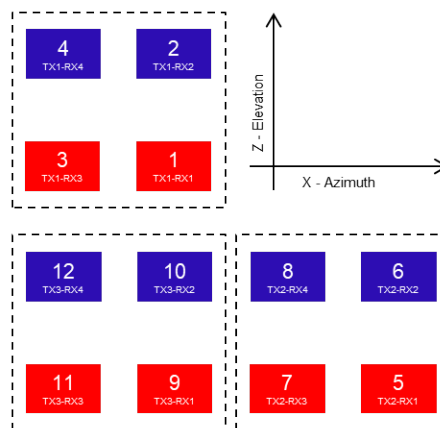
RX1 and RX3 are 180° out of phase with respect to RX2 and RX4. Because of this, a 180° phase inversion needs to be applied in software processing for the corresponding virtual RX channels (highlighted in Red)

Figure 5-11. xWR6843AoP ES1.0 Antenna Geometry

5.12 xWR6843AoP ES2.0 Antenna Geometry



MIMO Virtual
Antenna Array



RX1 and RX3 are 180° out of phase with respect to RX2 and RX4, similar to ES1. Because of this, a 180° phase inversion needs to be applied in software processing for the corresponding virtual RX channels (highlighted in Red)

Figure 5-12. xWR6843AoP ES2.0 Antenna Geometry

5.13 xWR6843AoP ES2.0 Antenna Geometry Code Update

MMWAVE-SDK 3.2.0.6 vs MMWAVE-SDK 3.4

File: mmwave_sdk_03_04_00_0x\packages\ti\board\antenna_geometry.c

C:\ti\mmwave_sdk_03_02_06_AOP\packages\ti\board\antenna_geometry.c	C:\ti\mmwave_sdk_03_04_00_03\packages\ti\board\antenna_geometry.c
5/31/2019 9:58:33 AM 2,822 bytes C,C++,C# Source ▾ ANSI ▾ UNIX	3/30/2020 6:14:33 PM 2,823 bytes C,C++,C# Source ▾ ANSI ▾ UNIX
<pre> 66 /** 67 * @brief Antenna geometry for IWR6843 AOP 68 * 69 */ 70 ANTDEF_AntGeometry gAntDef_IWR6843AOP = { 71 .txAnt = { 72 {0, 0}, 73 {0, 2}, 74 {2, 2} 75 }, 76 .rxAnt = { 77 {1, 0}, 78 {1, 1}, 79 {0, 0}, 80 {0, 1} 81 } 82 }; </pre>	<pre> 66 /** 67 * @brief Antenna geometry for IWR6843 AOP 68 * 69 */ 70 ANTDEF_AntGeometry gAntDef_IWR6843AOP = { 71 .txAnt = { 72 {0, 0}, 73 {2, 2}, 74 {0, 2} 75 }, 76 .rxAnt = { 77 {1, 1}, 78 {1, 0}, 79 {0, 1}, 80 {0, 0} 81 } 82 }; </pre>

Figure 5-13. SDK 3.2.0.6 Vs SDK 3.4: Antenna Geometry Update for xWR6843AoP ES2.0

5.14 Antenna Geometry Structure Usage in mmw demo

File: mmwave_sdk_03_04_00_0x\packages\ti\demo\xwr64xx\mmw\main.c

C:\ti\mmwave_sdk_03_04_00_03\packages\ti\demo\xwr64xx\mmw\main.c
3/30/2020 6:14:33 PM 137,509 bytes C,C++,C# Source ▾ ANSI ▾ UNIX
<pre> 1558 System_printf ("Error: Unable to get RF scale factor [Error:%d]\n", errCode); 1559 goto exit; 1560 } 1561 1562 /* Copy antenna geometry definition */ 1563 if defined(XWR68XX_AOP_ANTENNA_PATTERN) 1564 extern ANTDEF_AntGeometry gAntDef_IWR6843AOP; 1565 dataPathObj->objDetCommonCfg.preStartCommonCfg.antDef = gAntDef_IWR6843AOP; 1566 else 1567 extern ANTDEF_AntGeometry gAntDef_default; 1568 dataPathObj->objDetCommonCfg.preStartCommonCfg.antDef = gAntDef_default; 1569 endif 1570 1571 /* DPC pre-start common config */ 1572 errCode = DPM_ioctl (dataPathObj->objDetDpmHandle, 1573 DPC_OBJDET_IOCTL_STATIC_PRE_START_COMMON_CFG, 1574 &dataPathObj->objDetCommonCfg.preStartCommonCfg, 1575 sizeof (DPC_ObjectDetection_PreStartCommonCfg)); 1576 1577 if (errCode < 0) 1578 { 1579 System_printf ("Error: Unable to send DPC_OBJDET_IOCTL_STATIC_PRE_START_COMMON_CFG [Error:%d]\n", errCode); 1580 goto exit; 1581 } </pre>

Figure 5-14. Antenna Geometry Structure Usage in mmw demo

5.15 xWR6843AoP ES2.0 RX Channel Phase Compensation

MMWAVE-SDK 3.2.0.6 vs MMWAVE-SDK 3.4

File: mmwave_sdk_03_04_00_03\packages\ti\demo\xwr64xx\mmw\profiles\profile_3d_aop.cfg

<pre> C:\ti\mmwave_sdk_03_02_00_06_AOP\packages\ti\demo\xwr64xx\mmw\profiles\profile_3d_aop.cfg 5/31/2019 9:58:33 AM 2,717 bytes <default> ANSI UNIX 37 flushCfg 38 dfeDataOutputMode 1 39 channelCfg 15 7 0 40 adcCfg 2 1 41 adcbuffCfg -1 0 1 1 1 42 lowPower 0 0 43 profileCfg 0 60.25 7 3 24 0 0 156 1 256 12500 0 0 30 44 chirpCfg 0 0 0 0 0 0 1 45 chirpCfg 1 1 0 0 0 0 2 46 chirpCfg 2 2 0 0 0 0 4 47 frameCfg 0 2 32 0 100 1 0 48 guiMonitor -1 1 1 1 0 0 1 49 cfarCfg -1 0 2 8 4 3 0 15.0 0 50 cfarCfg -1 1 0 4 2 3 1 15.0 0 51 multiObjBeamForming -1 1 0.5 52 calibDcRangeSig -1 0 -5 8 256 53 clutterRemoval -1 0 54 55 compRangeBiasAndRxChanPhase 0.0 -1 0 1 0 -1 0 1 0 -1 0 1 0 -1 0 1 0 -1 0 1 0 -1 0 1 0 56 measureRangeBiasAndRxChanPhase 0 1. 0.2 57 58 aoaFovCfg -1 -90 90 -90 90 59 cfarFovCfg -1 0 0.25 15 60 cfarFovCfg -1 1 -13.39 13.39 61 extendedMaxVelocity -1 0 62 63 CQRxSatMonitor 0 3 4 63 0 64 CQSigImgMonitor 0 127 4 65 analogMonitor 0 0 66 lvsStreamCfg -1 0 0 0 67 sensorStart </pre>	<pre> C:\ti\mmwave_sdk_03_04_00_03\packages\ti\demo\xwr64xx\mmw\profiles\profile_3d_aop.cfg 3/30/2020 6:14:33 PM 2,717 bytes <default> ANSI UNIX 37 flushCfg 38 dfeDataOutputMode 1 39 channelCfg 15 7 0 40 adcCfg 2 1 41 adcbuffCfg -1 0 1 1 1 42 lowPower 0 0 43 profileCfg 0 60.25 7 3 24 0 0 156 1 256 12500 0 0 30 44 chirpCfg 0 0 0 0 0 0 1 45 chirpCfg 1 1 0 0 0 0 2 46 chirpCfg 2 2 0 0 0 0 4 47 frameCfg 0 2 32 0 100 1 0 48 guiMonitor -1 1 1 1 0 0 1 49 cfarCfg -1 0 2 8 4 3 0 15.0 0 50 cfarCfg -1 1 0 4 2 3 1 15.0 0 51 multiObjBeamForming -1 1 0.5 52 calibDcRangeSig -1 0 -5 8 256 53 clutterRemoval -1 0 54 55 compRangeBiasAndRxChanPhase 0.0 1 0 -1 0 1 0 -1 0 1 0 -1 0 1 0 -1 0 1 0 -1 0 1 0 -1 0 56 measureRangeBiasAndRxChanPhase 0 1. 0.2 57 58 aoaFovCfg -1 -90 90 -90 90 59 cfarFovCfg -1 0 0.25 15 60 cfarFovCfg -1 1 -13.39 13.39 61 extendedMaxVelocity -1 0 62 63 CQRxSatMonitor 0 3 4 63 0 64 CQSigImgMonitor 0 127 4 65 analogMonitor 0 0 66 lvsStreamCfg -1 0 0 0 67 sensorStart </pre>
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Figure 5-15. SDK 3.2.0.6 Vs SDK 3.4: RX Channel Phase Compensation

6 References

- Texas Instruments: [IWR1642 Device Errata](#)
- Texas Instruments: [AWR1642 Device Errata](#)
- Texas Instruments: [IWR1843 Device Errata](#)
- Texas Instruments: [AWR1843 Device Errata](#)
- Texas Instruments: [IWR6843 Device Errata](#)
- Texas Instruments: [AWR6843 Device Errata](#)
- [xWR1642BOOST Layout and Design Files](#)
- [xWR6843AOPEVM Schematic, Assembly and Bill of Materials](#)
- Texas Instruments: [xWR1642 EVM \(xWR1642BOOST\) Single-Chip mmWave Sensing Solution User's Guide](#)
- Texas Instruments: [MMWAVEICBOOST and Antenna Module User's Guide](#)
- [xWR6843 Checklist for Schematic Review, Layout Review, Bringup/Wakeup](#)
- [xWR1843BOOST Hardware Files](#)
- Texas Instruments: [xWR1843 Evaluation Module \(xWR1843BOOST\) Single-Chip mmWave Sensing Solution User's Guide](#)
- [xWR6843 Product Page](#) (Device data sheet, Silicon Errata)
- [xWR6843AoP Product Page](#) (Device data sheet, Silicon Errata)
- [xWR1843 Product Page](#) (Device data sheet, Silicon Errata)
- [xWR1642 Product Page](#) (Device data sheet, Silicon Errata)
- Texas Instruments: [IWR14xx/16xx/18xx/68xx Industrial Radar Family Technical Reference Manual](#)
- [MMWAVE-SDK Product Page](#)
- [MMWAVE-SDK 3.3.0 download page](#) (Release notes, User guide and SDK download)
- [MMWAVE-SDK 3.4.0 download page](#) (Release notes, User guide and SDK download)

7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision B (May 2022) to Revision C (October 2022)	Page
• Updated the numbering format for tables, figures, and cross-references throughout the document.....	3
Changes from Revision * (November 2019) to Revision A (May 2020)	Page
• Updates were made in Device Comparison topic.....	4
• Added new Section 2.1.2	5
• Updates were made in Section 2.1.2.1	5
• Added new Section 2.1.3	6
• Updates were made in Hardware Changes From xWR6843AoP ES1.0 to xWR6843AoP ES2.0 topic.....	9
• Update was made in Software Migration From xWR6843AoP ES1.0 to xWR6843AoP ES2.0 topic.....	11

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