

Power Management Optimizations – Low Cost LC Filter Solution



Abdulraheem Killedar

ABSTRACT

This application report discusses the Power supply ripple and noise specifications, reference solutions and introduces its trade off, an LC filter-based low cost solution.

Table of Contents

Trademarks.....	1
1 Introduction.....	2
2 Power Supply Ripple and Noise Specifications.....	2
3 Reference Solution.....	4
4 Low Cost LC Filter Solution.....	6
4.1 LDO vs LC Filter Scheme Comparison.....	6
4.2 System Tests.....	9
5 Summary.....	19

List of Figures

Figure 3-1. Power Management Scheme With LDOs.....	4
Figure 3-2. Reference Schematic.....	5
Figure 4-1. Power Management Scheme With LC filter.....	6
Figure 4-2. Capture With LDO Scheme, RX Gain-48dB.....	10
Figure 4-3. Capture With LDO Scheme, RX Gain-30dB.....	11
Figure 4-4. Capture With LC Filter Scheme, RX Gain-48dB.....	12
Figure 4-5. Capture With LC Filter Scheme, RX Gain-30dB.....	13
Figure 4-6. LDO Scheme –Spur Level.....	15
Figure 4-7. LDO Scheme - Noise Floor With Tx –OFF.....	16
Figure 4-8. LC Filter Scheme – Spur Level.....	17
Figure 4-9. LC Filter Scheme - Noise Floor With Tx –OFF.....	18

List of Tables

Table 2-1. XWR1xx Supply Ripple (μVrms).....	2
Table 2-2. XWR1xx Noise Spectral Density ($\mu\text{Vrms/RtHz}$).....	2
Table 2-3. XWR1xxx Supply Ripple (μVrms).....	3
Table 2-4. XWR1xxx Noise Spectral Density ($\mu\text{Vrms/RtHz}$).....	3
Table 4-1. Recommended Ferrite Bead Components.....	6
Table 4-2. Sensor Configuration.....	6
Table 4-3. Spur/Noise Level Measurements With Tx to Rx Waveguide Loopback.....	7
Table 4-4. Voltage Transient Behavior.....	8
Table 4-5. Sensor Configuration.....	9
Table 4-6. SNR Comparison Between LDO and LC Filter Scheme for RX Gain = 30 and 48.....	14

Trademarks

All trademarks are the property of their respective owners.

1 Introduction

XWR1xx is a family of Texas Instrument's mmWave Radar sensor devices with RFCMOS technology. These devices are intended for the automotive and industrial applications. The devices are powered by four voltage rails, namely 3.3 V, 1.2 V, 1.8 V and 1.0 V.

Contents of this document apply to the following mmWave devices:

- xWR1xxx/xWR2xxx
- xWR6xxx

2 Power Supply Ripple and Noise Specifications

Out of the four Power supply rails mentioned above, the 1.0 V and the 1.8 V supplies are sensitive to the supply ripple and noise because these supplies feed the critical blocks in the device like PLL, baseband ADC, synthesizer, and so forth. For more details on the power supply rail and the logic that it feeds in the device, see the device-specific data sheet. [Table 2-1](#) and [Table 2-2](#) provide the ripple and noise spec for 1.0 V

Table 2-1. XWR1xx Supply Ripple (μVrms)

Sl. Number	Frequency (KHz)	XWR1xx Supply Ripple (μVrms)
1	17.1875	
2	34.375	
3	68.75	
4	137.5	
5	275	
6	550	
7	1100	
8	2200	
9	4400	35.48133892
10	6600	

Table 2-2. XWR1xx Noise Spectral Density ($\mu\text{Vrms/RtHz}$)

Sl. Number	Frequency (KHz)	XWR1xx Noise Spectral Density ($\mu\text{Vrms/RtHz}$)
1	17.1875	0.01
2	34.375	0.01
3	68.75	0.01
4	137.5	0.015
5	275	0.02
6	550	0.02
7	1100	0.009
8	2200	0.002
9	4400	0.05
10	6600	0.002

Table 2-3 and Table 2-4 provide the ripple and noise spec for 1.8 V.

Table 2-3. XWR1xxx Supply Ripple (μVrms)

SI Number	Frequency (KHz)	XWR1xxx Supply Ripple (μVrms)
1	17.1875	
2	34.375	
3	68.75	
4	137.5	
5	275	
6	550	
7	1100	
8	2200	
9	4400	35.48133892
10	6600	

Table 2-4. XWR1xxx Noise Spectral Density ($\mu\text{Vrms}/\text{RtHz}$)

SI Number	Frequency (KHz)	XWR1xxx Noise Spectral Density ($\mu\text{Vrms}/\text{RtHz}$)
1	17.1875	0.08
2	34.375	0.07
3	68.75	0.07
4	137.5	0.07
5	275	0.07
6	550	0.07
7	1100	0.07
8	2200	0.07
9	4400	0.07
10	6600	0.07

3 Reference Solution

TI recommends the reference solution with the PMIC and the LDOs as shown in [Figure 3-1](#), which is also incorporated in the XWR1xxx EVMs. The reference solution meets these specifications. The XWR1xx device would expect 1.0 V to be fed on the H5, G5, J5, D2 and C2 pins. The PMIC needs to be reconfigured for the Buck outputs shown in [Figure 3-1](#) using the Inter-Integrated Circuit (I2C) interface from the host. Initially during the power up, the buck outputs would be 3.3 V, 1.2 V, 1.3 V and 2.1 V. Using I2C interface, the buck outputs needs to be reconfigured as shown in [Figure 3-1](#) before the nRESET of XWR1xx is released.

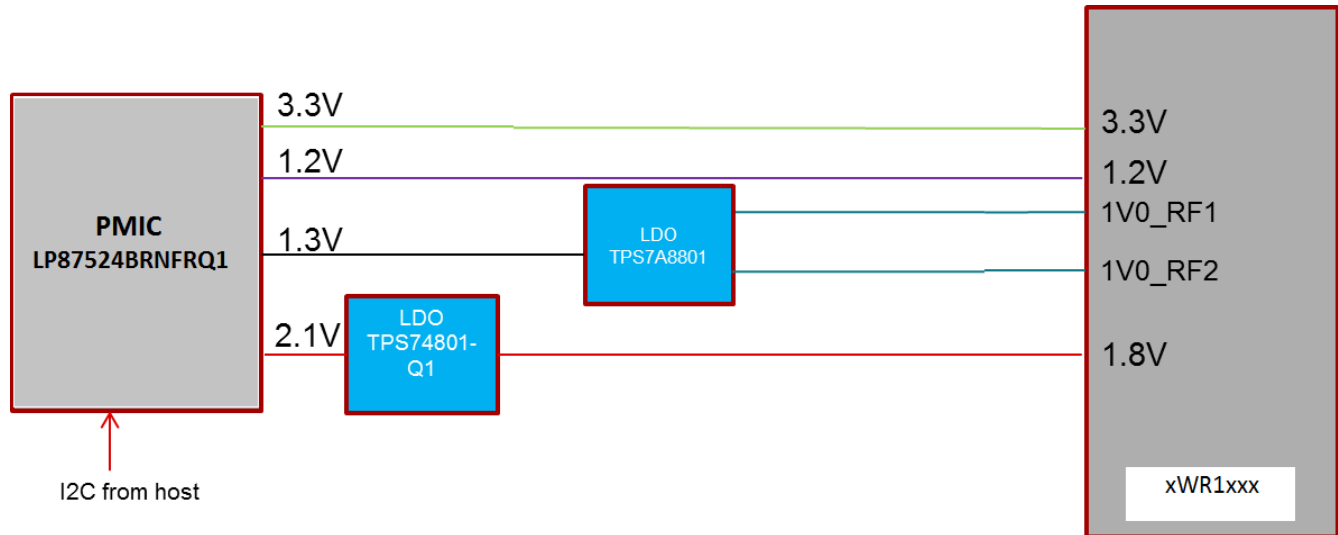


Figure 3-1. Power Management Scheme With LDOs

The above reference solution consists of the LP87524BRNFRQ1 PMIC with the switching frequency localized at 4 MHz, so that the fundamental and the harmonics could easily be filtered out during RADAR data post processing. The reference schematic is shown in [Figure 3-2](#).

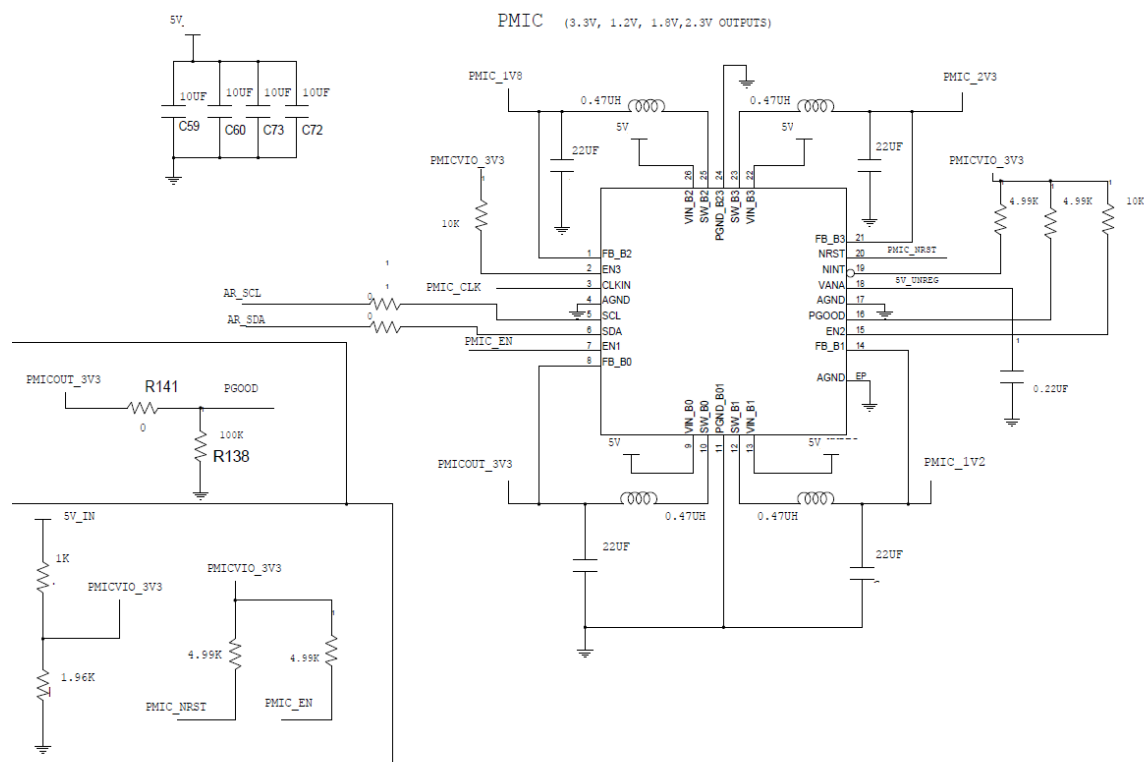


Figure 3-2. Reference Schematic

4 Low Cost LC Filter Solution

For the cost sensitive use cases, a low cost LC filter (Ferrite bead + Device Decoupling capacitor) based solution could be used, which would effectively replace the LDOs on the 1.8 V and 1.0 V rails. This approach would have performance and the system level trade-off.

Figure 4-1 shows the Power management scheme.

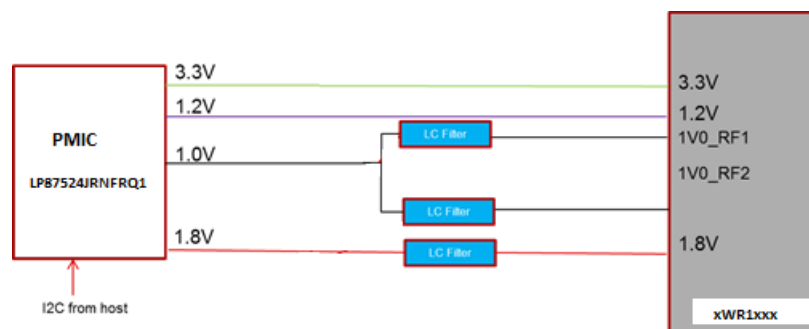


Figure 4-1. Power Management Scheme With LC filter

Note

The capacitors shown above in the LC filter are the device decoupling capacitors.

The recommended Ferrite bead components are shown in Table 4-1.

Table 4-1. Recommended Ferrite Bead Components

LC Filter	Inductor Value (μH)	DC Resistance (mΩ)	Impedance @ 100 MHz (Ω)	Size (inches)	Pole Frequencies w.r.t. 1V Rail Decaps/1.8V Rail Decaps (KHz)	DC Current (A)	Theoretical Rejection Offered by the Filter (dB)	Manufacturer Part Number
Ferrite Bead	0.1909	25	120	0603	113.9	3	64	BLM18KG121 TH1

4.1 LDO vs LC Filter Scheme Comparison

4.1.1 Waveguide Loopback Tests

Two consecutive chirps have been analyzed with 10 μSec and 100 μSec of idle time and the below chirp configuration.

Table 4-2 provides the sensor configuration for the below tests.

Table 4-2. Sensor Configuration

Parameter	Value
Start frequency (GHz)	77
Frequency slope (MHz)	35.003
Tx start time (μsec)	0
ADC start time (μsec)	5
ADC samples	1024
Sample rate (Kbps)	10000
Ramp end time (μsec)	110
Rx gain	33

4.1.2 Spur/Noise Floor Level

The measurements shown in [Table 4-3](#) are done with TX to RX loopback with Tx Back-Off=0 and Complex Rx gain=33dB.

Table 4-3. Spur/Noise Level Measurements With Tx to Rx Waveguide Loopback

PM Scheme	Idle Channel Noise Floor (Rx-alone) at the ADC Output (dBFs/Hz)	Amplitude Level of PMIC Ripple Frequency Spur (4.05M-4.17M) Seen at the ADC Output (dBFs)	(Tx+Rx) SNR dBc/Hz	Amplitude Level of PMIC Ripple Frequency Spur (4.05M-4.17M) Seen at the ADC Output (dBFs)
	Additive (Rx1 - alone)		Loop back (Tx2-Rx1)	
LDO Scheme	-138.80	Not seen	-118.74	Not seen (less than noise floor)
LC Filter Scheme	-138.27	Not seen	-120.6	-104

4.1.3 Voltage Transient Behavior

Table 4-4. Voltage Transient Behavior

PM Scheme	XWR1xx Supply Rail	Voltage Setting Parameters on Chirp 1				Voltage Setting Parameters on Chirp 2				Steady State DC Value (mV) at the Input of XWR1642 Rail	Calculated IR Drop (mV) (difference between steady state DC and actual input voltage)
		Undershoot Voltage (mV)		Undershoot Period (μs)		Undershoot Voltage (mV)		Undershoot Period (μs)			
	Idle time (μs)	10	100	10	100	10	100	10	100	10	10/100
LDO	RF1_1V0	55.6	79.0	4.4	6.7	67.0	214.5	5.0	10.0	982.0	17
	RF2_1V0	33.9	34.6	7.2	11.1	42.0	208.3	5.6	12.2	982.0	17
	CLK_1V8	20.0	20.0	1.6	2.5	24.0	20.0	2.4	2.6	1760.0	35
LC Filter	RF1_1V0	59.0	51.2	6.2	6.1	59.0	51.2	4.4	5.0	949.5	49.5
	RF2_1V0	44.1	47.0	5.9	5.5	44.1	41.1	4.3	5.7	944.6	54.4
	CLK_1V8	30.5	17.9	3.1	4.0	30.5	17.9	3.5	3.5	1737.0	58

4.2 System Tests

4.2.1 Sensor Configuration

Table 4-5. Sensor Configuration

Parameter	Value	Comments
Start frequency (GHz)	77	
Frequency slope (MHz)	68.65	
Tx start time (uSec)	0	
ADC start time (uSec)	5.99	
Idle time (uSec)	12	Inter Chirp power saving enabled for idle time+Tx start time >10usec
ADC samples	256	
Sample rate (Kbps)	5000	
Ramp end time	58.22	
Rx gain	48	

4.2.2 System Test With Static Object

The test involves detecting an object at approximately 1m from the sensor. Both captures with LDO and LC filter schemes are shown below. No major degradation in the signal power is detected as shown below.

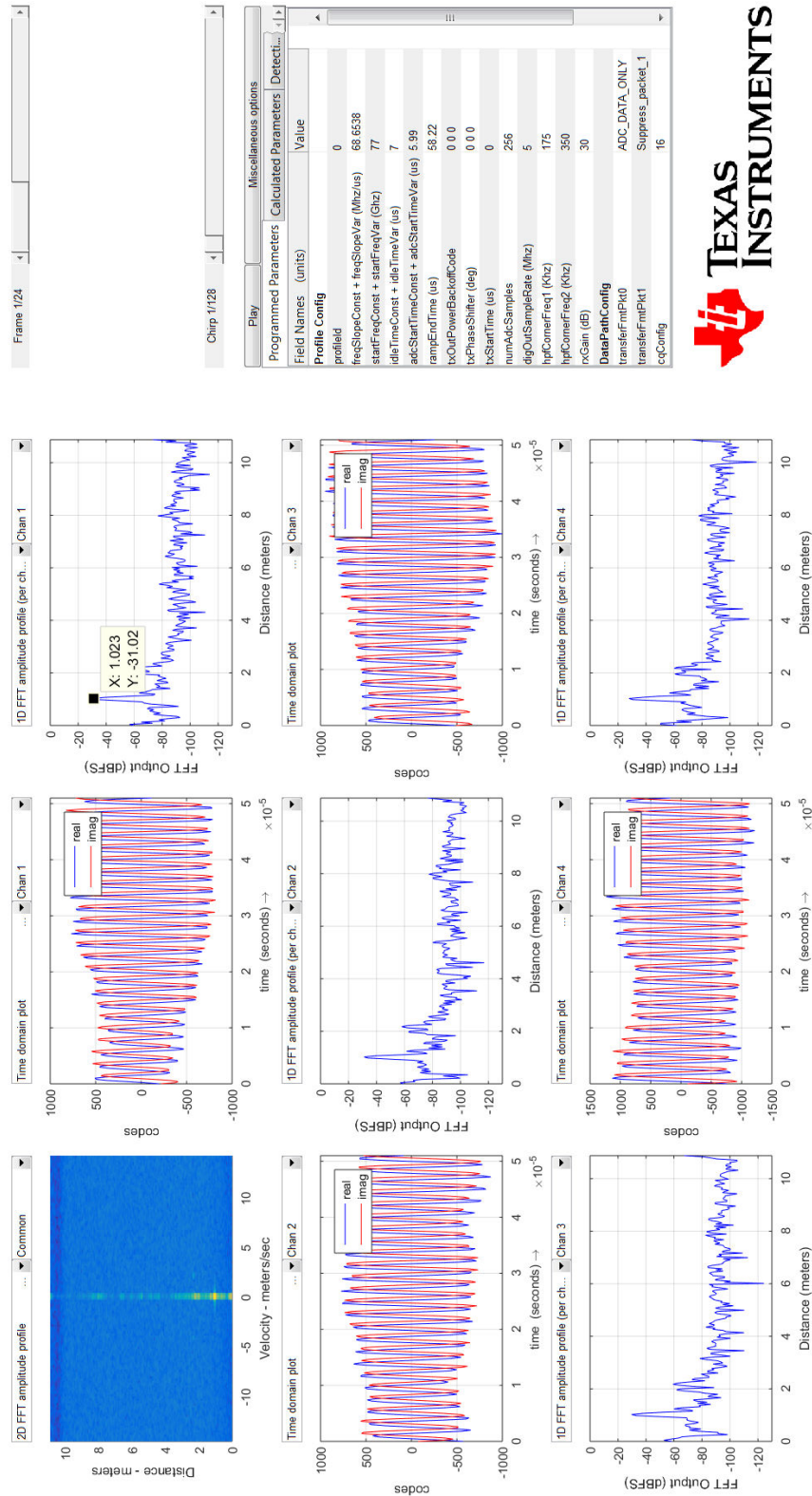


Figure 4-2. Capture With LDO Scheme, RX Gain-48dB



Copyright © 2020 Texas Instruments Incorporated

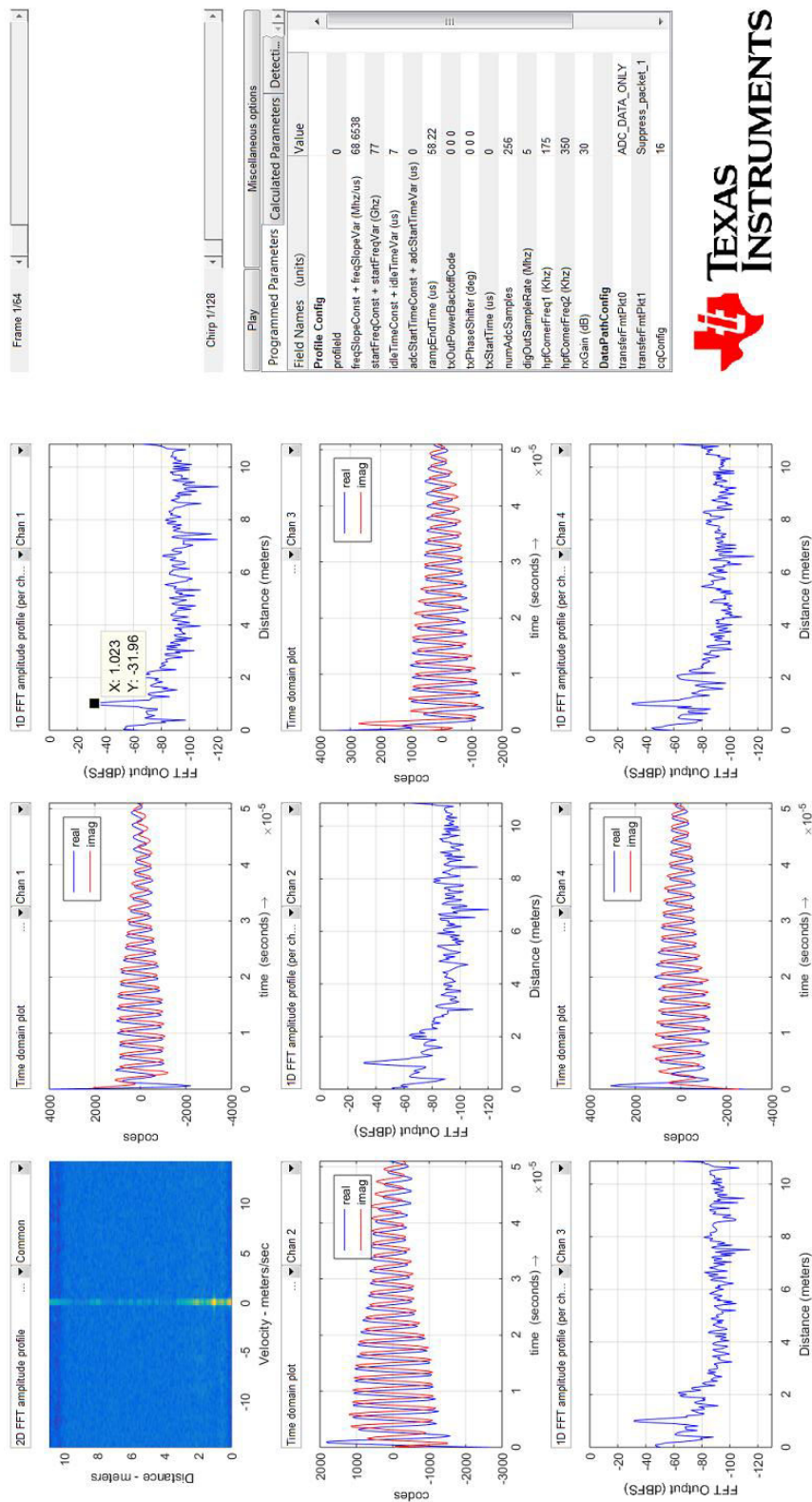


Figure 4-4. Capture With LC Filter Scheme, RX Gain-48dB

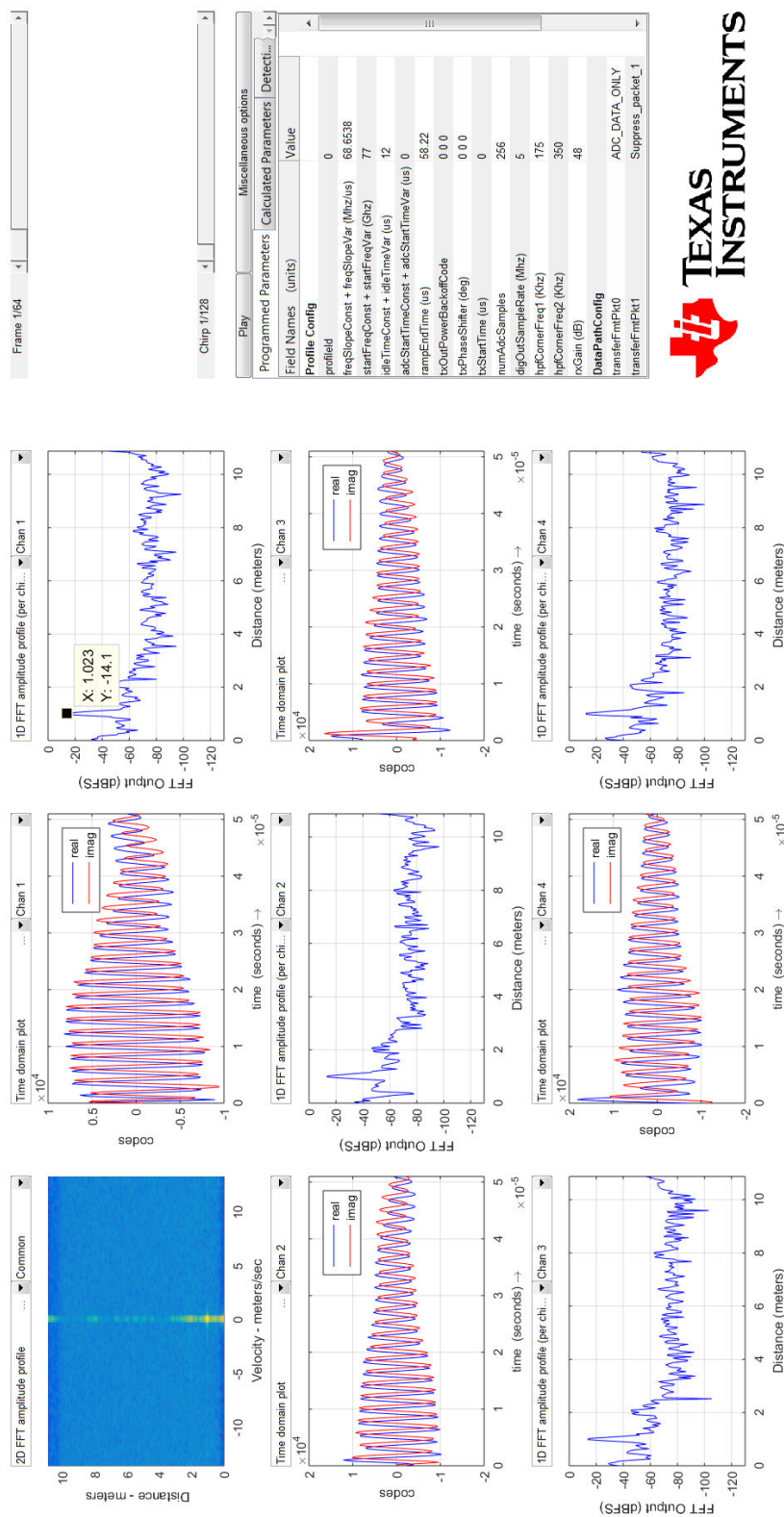


Figure 4-5. Capture With LC Filter Scheme, RX Gain-30dB

Table 4-6. SNR Comparison Between LDO and LC Filter Scheme for RX Gain = 30 and 48

PM Scheme	RX Gain(dB)	SNR(dB)-RBW 152.6Hz
LDO	30	81.93
	48	83.9
LC Filter	30	79.6
	48	81.9

4.2.3 Spur/Noise Floor Level

For Spur level measurements, a continuous tone at 77 GHz is transmitted and the received signal is analyzed with 524288 samples for the presence of the PMIC switching frequency spur at ~4 MHz. The Rx gain is set at 48dB with an observation that PMIC spur level tracks the Rx gain.

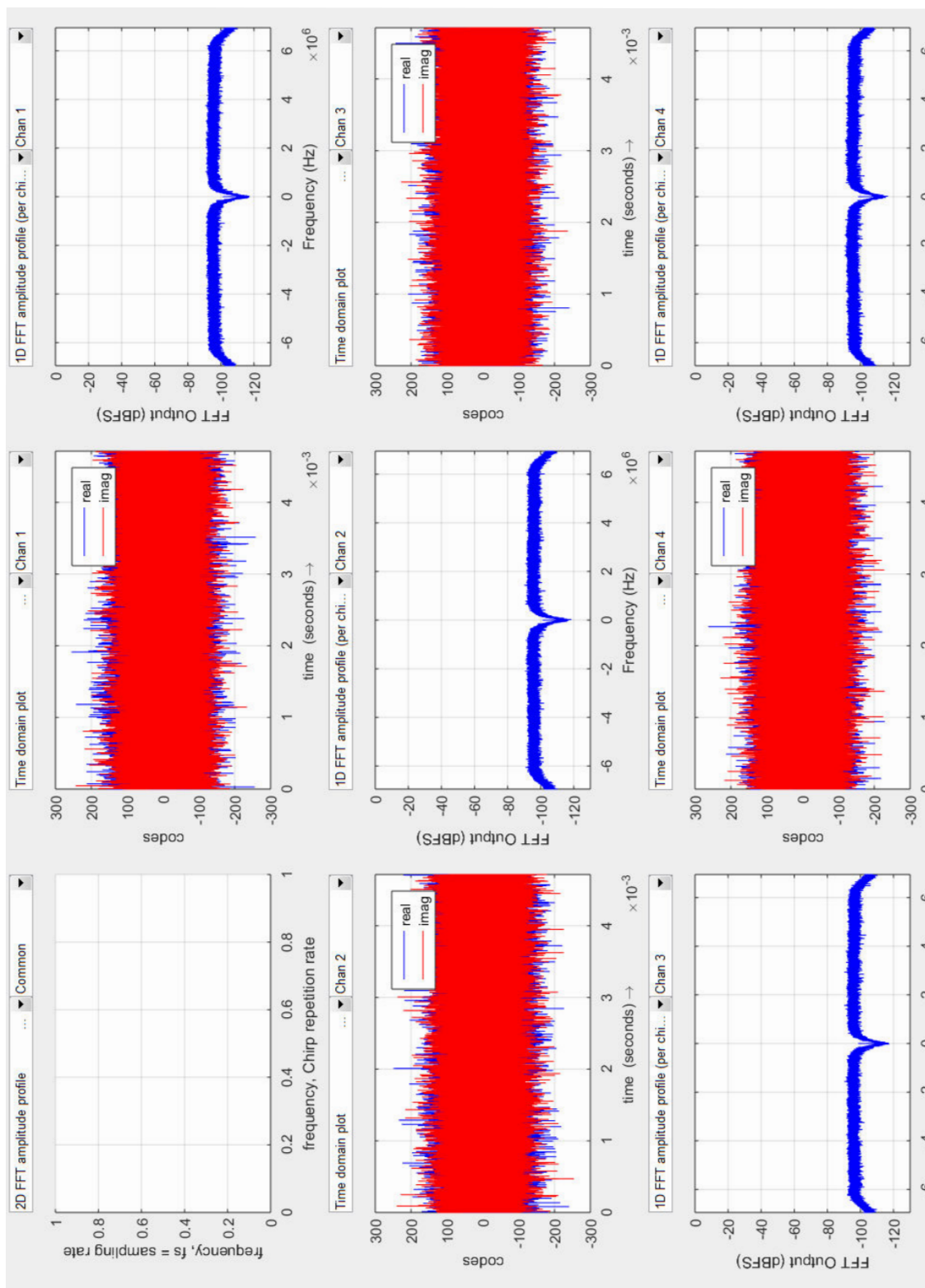


Figure 4-6. LDO Scheme –Spur Level

Note

No PMIC switching Frequency (approximately 4 MHz) Spur seen.

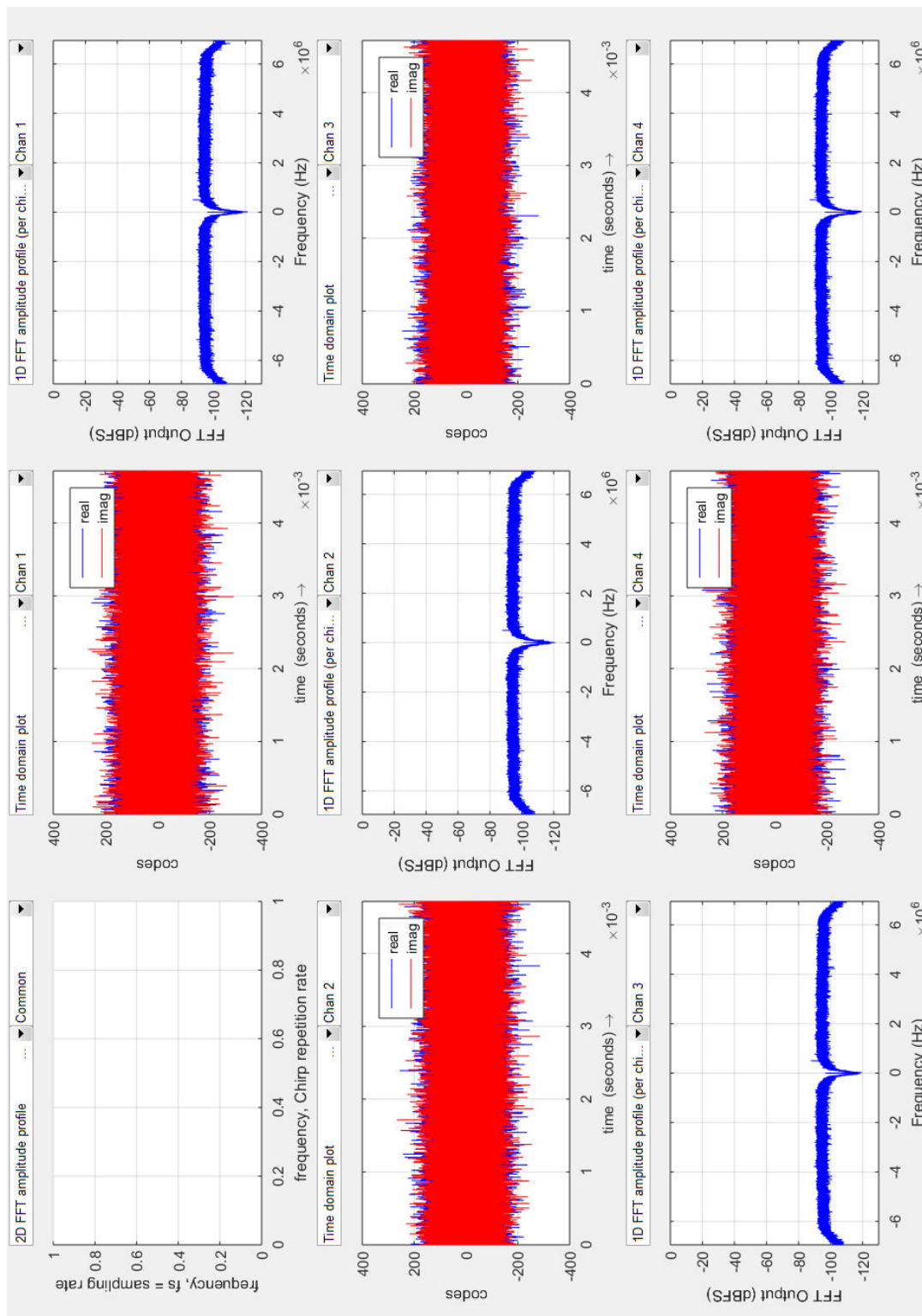


Figure 4-7. LDO Scheme - Noise Floor With Tx –OFF

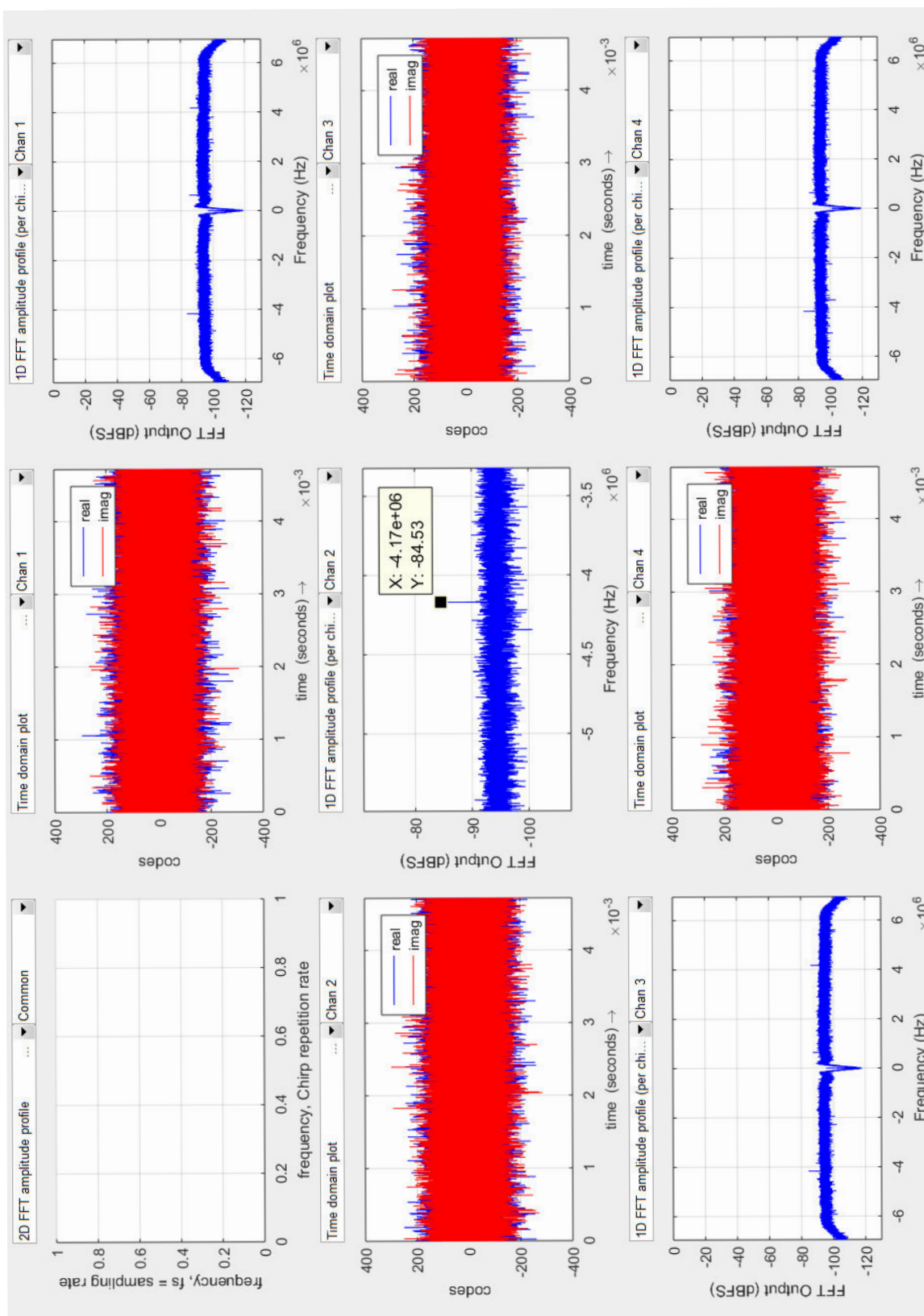


Figure 4-8. LC Filter Scheme – Spur Level

Note

PMIC spur is observed at -84.53 dBFS at RX gain of 48dB.

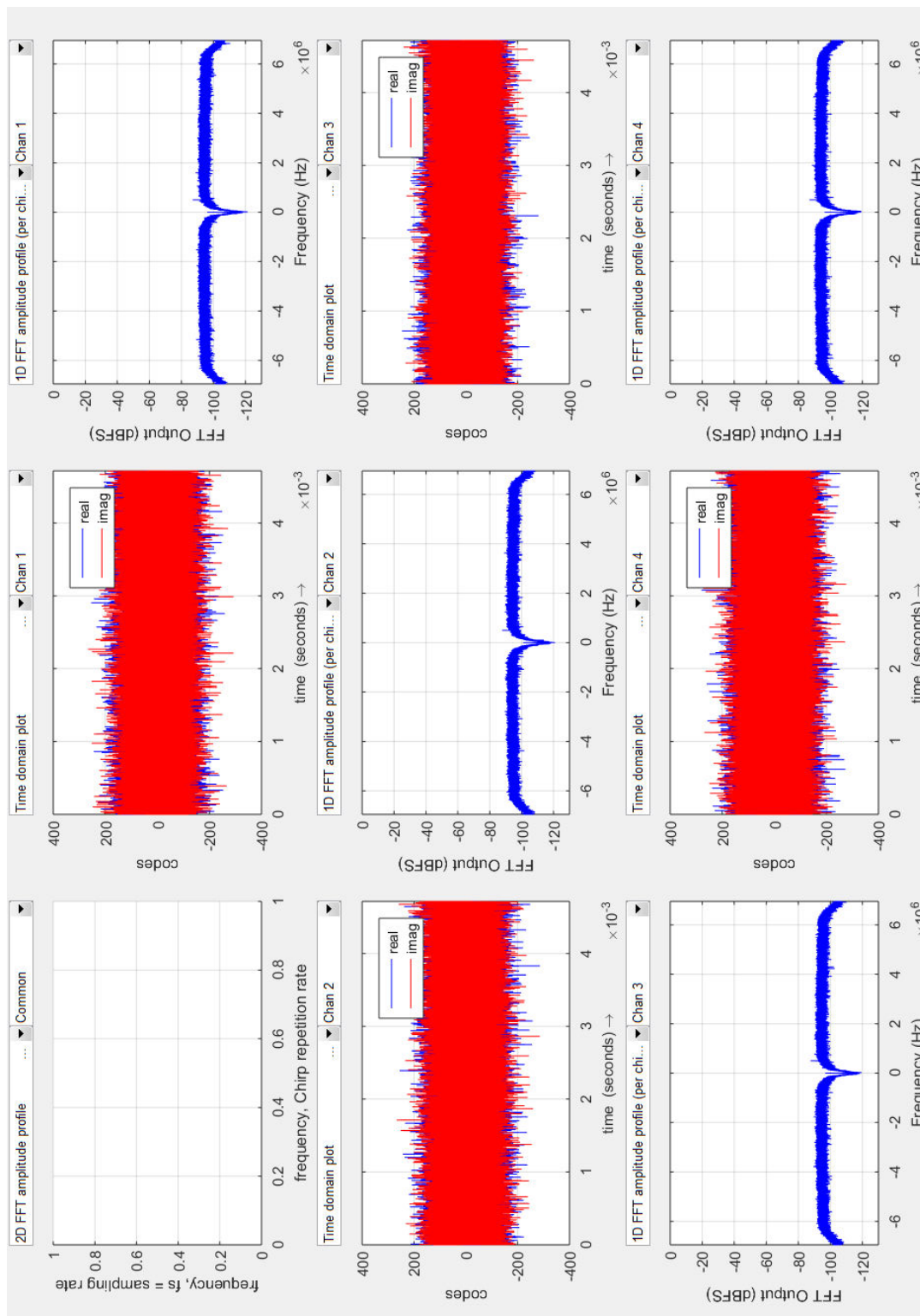


Figure 4-9. LC Filter Scheme - Noise Floor With Tx –OFF

5 Summary

This application report proposes two power management schemes for XWR1xxx devices. [Section 4](#) puts forth an optimal scheme with respect to bill of material and power dissipation, using LC filters. [Section 3](#) explains a scheme using LDOs for achieving better power supply ripple/noise rejection. The LC Filter solution scores better on the Cost and overall System Power saving front in comparison to the LDO scheme."

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](#) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2022, Texas Instruments Incorporated